

CLC1005, CLC1015, CLC2005

Low Cost, +2.7V to 5.5V, 260MHz Rail-to-Rail Amplifiers

General Description

The CLC1005 (single), CLC1015 (single with disable), and CLC2005 (dual) are low cost, voltage feedback amplifiers. These amplifiers are designed to operate on +2.7V to +5V, or ±2.5V supplies. The input voltage range extends 300mV below the negative rail and 1.2V below the positive rail.

The CLC1005, CLC1015, and CLC2005 offer superior dynamic performance with 260MHz small signal bandwidth and 145V/µs slew rate. The amplifiers consume only 4.2mA of supply current per channel and the CLC1015 offers a disable supply current of only 127µA. The combination of low power, high output current drive, and rail-to-rail performance make these amplifiers well suited for battery-powered communication/computing systems.

The combination of low cost and high performance make the CLC1005; is in whiteboan ssion. The data drawn of the dat consumer and industrial applications such as interactive whiteboards wireless phones, scanners color copiers, and vides transfer to the consumer and industrial applications such as interactive whiteboards. CLC1015, and CLC2005 suitable for high volume applications in both wireless phones, scanners, color copiers, and video transmission

FEATURES

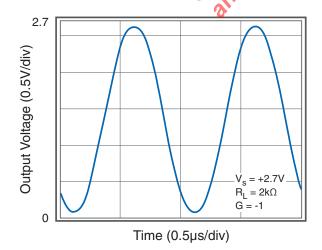
- 260MHz bandwidth
- Fully specified at +2.7V and +5V supplies
- Output voltage range:
 - \circ 0.036V to 4.953V; $V_S = +5$; $R_L = 2k\Omega$
- Input voltage range:
 - -0.3V to +3.8V; $V_S = +5$
- 145V/µs slew rate
- 4.2mA supply current
- Power down to 127µA
- ±55mA linear output current
- ±85mA short circuit current
- CLC2005 directly replaces AD8052/42/92 in single supply applications
- CLC1005 directly replaces AD8051/41/91 in single supply applications

APPLICATIONS

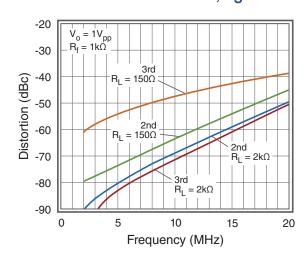
- A/D driver
- Active filters
- CCD imaging systems
- CD/DVD ROM
- Coaxial cable drivers
- High capacitive load driver
- Portable/battery-powered applications
- Twisted pair driver
- Telecom and optical terminals
- Video driver
- Interactive whiteboards

Ordering Information - backpage

Output Swing



2nd & 3rd Harmonic Distortion; $V_S = +2.7V$



Absolute Maximum Ratings

Stresses beyond the limits listed below may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

V _S	0V to +6V
V _{IN} V _S - 0.5V to -	+V _S +0.5V

Operating Conditions

Supply Voltage Range	2.5 to 5.5V
Operating Temperature Range	40°C to 85°C
Junction Temperature	150°C
Storage Temperature Range	65°C to 150°C
Lead Temperature (Soldering, 10s)	260°C

Package Thermal Resistance

θ _{JA} (SOIC-8)	150°C/W
θ _{JA} (MSOP-8)	200°C/W
θ _{JA} (TSOT23-5)	215°C/W
θ _{JA} (TSOT23-6)	192°C/W
θ_{JA} (TSOT23-6)	JEDEC standard, multi-layer

ESD Protection

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Electrical Characteristics at +2.7V

 T_A = 25°C, V_S = +2.7V, R_f = 2k Ω , R_L = 2k Ω to $V_S/2;$ G = 2; unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Frequency [Domain Response					
GBWP	-3dB Gain Bandwidth Product			86		MHz
UGBW	Unity Gain Bandwidth(1)	$G = +1, V_{OUT} = 0.05V_{pp}$		215		MHz
BW_{SS}	-3dB Bandwidth	$G = +2, V_{OUT} = 0.2V_{pp}$		85		MHz
BW _{LS}	Large Signal Bandwidth	$G = +2$, $V_{OUT} = 2V_{pp}$		36		MHz
Time Doma	in					
t _R , t _F	Rise and Fall Time (1)	V _{OUT} = 0.2V step; (10% to 90%)		3.7		ns
t _S	Settling Time to 0.1%	V _{OUT} = 1V step		40		ns
OS	Overshoot	V _{OUT} = 0.2V step		9		%
SR	Slew Rate	G = -1, 2.7V step		130		V/µs
Distortion/N	oise Response	the state of				
HD2	2nd Harmonic Distortion (1)	5MHz, V _{OUT} = 1V _{pp}		79		dBc
HD3	3rd Harmonic Distortion (1)	5MHz, V _{OUT} = 1V _{pp}		82		dBc
THD	Total Harmonic Distortion (1)	5MHz, V _{OUT} = 1V _{pp}		77		dB
e _n	Input Voltage Noise	>1MHz		16		nV/√Hz
i _n	Input Current Noise	>1MHz		1.3		pA/√Hz
X _{TALK}	Crosstalk ⁽¹⁾	CLC2005, 10MHz		65		dB
DC Perform	ance	mins-				
V _{IO}	Input Offset Voltage	6 20 00		-1.6		mV
d _{VIO}	Average Drift	(2), (2)		10		μV/°C
I _B	Input Bias Current	111 46, 1		3		μΑ
dl _B	Average Drift	00,00		7		nA/°C
I _{OS}	Input Offset Current	01000		0.1		μΑ
PSRR	Power Supply Rejection Ratio	(DO O 10	52	57		dB
A _{OL}	Open Loop Gain	0, 1, 0,		75		dB
I _S	Supply Current	10,00		3.9		mA
Disable Cha	aracteristics (CLC1015)	10 K				
T _{ON}	Turn On Time	200		150		ns
T _{OFF}	Turn Off Time			25		ns
OFFISO	Off Isolation	5MHz, $R_L = 100Ω$		75		dB
I _{SD}	Disable Supply Current	DIS tied to GND		58	100	μΑ
Input Chara	cteristics					
R _{IN}	Input Resistance			4.3		ΜΩ
C _{IN}	Input Capacitance			1.8		pF
CMIR	Common Mode Input Range			-0.3 to 1.5		V
CMRR	Common Mode Rejection Ratio	DC, $V_{CM} = 0$ to $V_{S} - 1.5V$		87		dB
Output Cha	racteristics			. '		
		$R_L = 10k\Omega$ to $V_S/2$		0.023 to 2.66		V
V_{OUT}	Output Swing	$R_L = 2k\Omega$ to $V_S/2$		0.025 to 2.653		V
		$R_L = 150\Omega$ to $V_S/2$		0.065 to 2.55		V
I _{OUT}	Output Current			±55		mA
001		-40°C to +85°C		±50		mA
I _{SC}	Short Circuit Current	$V_{OUT} = V_S / 2$		±85		mA
V _S	Power Supply Operating Range		2.5	2.7	5.5	V

Notes:

^{1.} $R_f=1k\Omega$ was used for optimal performance. (For $G=+1,\ R_f=0)$

Electrical Characteristics at +5V

 T_A = 25°C, V_S = +5V, R_f = 2k Ω , R_L = 2k Ω to $V_S/2;$ G = 2; unless otherwise noted.

GBWP UGBW BWSS BWLS Time Domain tR, tF tS OS SR Distortion/Nois HD2 HD3 THD DG	2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	$G = +1, V_{OUT} = 0.05V_{pp}$ $G = +2, V_{OUT} = 0.2V_{pp}$ $G = +2, V_{OUT} = 2V_{pp}$ $V_{OUT} = 0.2V \text{ step}$ $V_{OUT} = 2V \text{ step}$ $V_{OUT} = 0.2V \text{ step}$ $G = -1, 5V \text{ step}$ $5MHz, V_{OUT} = 2V_{pp}$ $5MHz, V_{OUT} = 2V_{pp}$ $5MHz, V_{OUT} = 2V_{pp}$ $TSC (3.85MHz), AC-Coupled, R = 150\Omega$		90 260 90 40 3.6 40 7 145		MHz MHz MHz MHz ns ns v/µs dBc dBc
UGBW BW _{SS} BW _{LS} Time Domain t _R , t _F t _S OS SR Distortion/Nois HD2 HD3 THD DG	Unity Gain Bandwidth ⁽¹⁾ -3dB Bandwidth Large Signal Bandwidth Rise and Fall Time ⁽¹⁾ Settling Time to 0.1% Overshoot Slew Rate se Response 2nd Harmonic Distortion ⁽¹⁾ 3rd Harmonic Distortion ⁽¹⁾ Total Harmonic Distortion ⁽¹⁾ Differential Gain	$G = +2, V_{OUT} = 0.2V_{pp}$ $G = +2, V_{OUT} = 2V_{pp}$ $V_{OUT} = 0.2V \text{ step}$ $V_{OUT} = 2V \text{ step}$ $V_{OUT} = 0.2V \text{ step}$ $G = -1, 5V \text{ step}$ $5MHz, V_{OUT} = 2V_{pp}$ $5MHz, V_{OUT} = 2V_{pp}$ $5MHz, V_{OUT} = 2V_{pp}$ $TSC (3.85MHz), AC-Coupled, B = 150\Omega$		260 90 40 3.6 40 7 145		MHz MHz MHz ns ns v/ us dBc
BW _{SS} BW _{LS} Time Domain t _R , t _F t _S OS SR Distortion/Nois HD2 HD3 THD DG	-3dB Bandwidth Large Signal Bandwidth Rise and Fall Time (1) Settling Time to 0.1% Overshoot Slew Rate se Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	$G = +2, V_{OUT} = 0.2V_{pp}$ $G = +2, V_{OUT} = 2V_{pp}$ $V_{OUT} = 0.2V \text{ step}$ $V_{OUT} = 2V \text{ step}$ $V_{OUT} = 0.2V \text{ step}$ $G = -1, 5V \text{ step}$ $5MHz, V_{OUT} = 2V_{pp}$ $5MHz, V_{OUT} = 2V_{pp}$ $5MHz, V_{OUT} = 2V_{pp}$ $TSC (3.85MHz), AC-Coupled, B = 150\Omega$		90 40 3.6 40 7 145		MHz MHz ns ns V/µs dBc
BW _{LS} Time Domain t _R , t _F t _S OS SR Distortion/Nois HD2 HD3 THD DG	Rise and Fall Time (1) Settling Time to 0.1% Overshoot Slew Rate se Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	$G = +2$, $V_{OUT} = 2V_{pp}$ $V_{OUT} = 0.2V$ step $V_{OUT} = 2V$ step $V_{OUT} = 0.2V$ step G = -1, $5V$ step $SMHz$, $V_{OUT} = 2V_{pp}$ $SMHz$, $V_{OUT} = 2V_{pp}$		3.6 40 7 145		ns ns % V/µs
Time Domain t _R , t _F t _S OS SR Distortion/Nois HD2 HD3 THD DG	Rise and Fall Time (1) Settling Time to 0.1% Overshoot Slew Rate See Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	V_{OUT} = 0.2V step V_{OUT} = 2V step V_{OUT} = 0.2V step G = -1, 5V step $SMHz, V_{OUT}$ = 2V _{pp}		3.6 40 7 145		ns ns % V/µs
t _R , t _F t _S OS SR Distortion/Nois HD2 HD3 THD DG	Settling Time to 0.1% Overshoot Slew Rate se Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	V_{OUT} = 2V step V_{OUT} = 0.2V step G = -1, 5V step 5MHz, V_{OUT} = 2V _{pp} 5MHz, V_{OUT} = 2V _{pp} 5MHz, V_{OUT} = 2V _{pp} NTSC (3.85MHz), AC-Coupled, B) = 150 Ω		40 7 145 71 78		ns % V/µs
ts OS SR Distortion/Nois HD2 HD3 THD DG	Settling Time to 0.1% Overshoot Slew Rate se Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	V_{OUT} = 2V step V_{OUT} = 0.2V step G = -1, 5V step 5MHz, V_{OUT} = 2V _{pp} 5MHz, V_{OUT} = 2V _{pp} 5MHz, V_{OUT} = 2V _{pp} NTSC (3.85MHz), AC-Coupled, B) = 150 Ω		40 7 145 71 78		ns % V/µs
OS SR Distortion/Nois HD2 HD3 THD DG	Overshoot Slew Rate se Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	V_{OUT} = 0.2V step G = -1, 5V step 5MHz, V_{OUT} = 2V _{pp} 5MHz, V_{OUT} = 2V _{pp} 5MHz, V_{OUT} = 2V _{pp} NTSC (3.85MHz), AC-Coupled, P_{OUT} = 150 Ω		7 145 71 78		% V/µs
SR Distortion/Nois HD2 HD3 THD DG	Slew Rate se Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	G = -1, $5V$ step $5MHz$, $V_{OUT} = 2V_{pp}$ $5MHz$, $V_{OUT} = 2V_{pp}$ $5MHz$, $V_{OUT} = 2V_{pp}$ $5MHz$, $V_{OUT} = 2V_{pp}$ $NTSC$ (3.85MHz), AC -Coupled, $B = 150\Omega$		71 78		V/µs
Distortion/Nois HD2 HD3 THD DG	See Response 2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	5 MHz, $V_{OUT} = 2V_{pp}$ 5 MHz, $V_{OUT} = 2V_{pp}$ 5 MHz, $V_{OUT} = 2V_{pp}$ NTSC (3.85MHz), AC-Coupled, $R_{A} = 150\Omega$		71 78		dBc
HD2 HD3 THD	2nd Harmonic Distortion (1) 3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	5 MHz, $V_{OUT} = 2V_{pp}$ 5 MHz, $V_{OUT} = 2V_{pp}$ NTSC (3.85MHz), AC-Coupled, $R_{A} = 150\Omega$		78		
HD3 THD DG	3rd Harmonic Distortion (1) Total Harmonic Distortion (1) Differential Gain	5 MHz, $V_{OUT} = 2V_{pp}$ 5 MHz, $V_{OUT} = 2V_{pp}$ NTSC (3.85MHz), AC-Coupled, $R_{A} = 150\Omega$		78		
THD DG	Total Harmonic Distortion (1) Differential Gain	5 MHz, $V_{OUT} = 2V_{pp}$ 5 MHz, $V_{OUT} = 2V_{pp}$ NTSC (3.85MHz), AC-Coupled, $R_{A} = 150\Omega$				dBc
DG	Differential Gain	NTSC (3.85MHz), AC-Coupled, $R_{\rm L}$ = 150 Ω		70		
		NTSC (3.85MHz), AC-Coupled, $R_{\rm L}$ = 150 Ω		1		dB
				0.06		%
DD		NTSC (3.85MHz), DC-Coupled, $R_L = 150\Omega$		0.08		%
		NTSC (3.85MHz), AC-Coupled, $R_L = 150\Omega$		0.07		0
DP	Differential Phase	NTSC (3.85MHz), DC-Coupled, $R_L = 150\Omega$		0.06		0
e _n	Input Voltage Noise	>1MHz		16		nV/√Hz
in	Input Current Noise	>1MHz		1.3		pA/√Hz
X _{TALK}	Crosstalk ⁽¹⁾	CLC2005, 10MHz		62		dB
DC Performan	nce	70 40 60				
V _{IO}	Input Offset Voltage	010,010	-8	1.4	8	mV
d _{VIO}	Average Drift	1,0,10		10		μV/°C
I _B	Input Bias Current	2, 4, 0,	-8	3	8	μA
dl _B	Average Drift	10.00		7		nA/°C
Ios	Input Offset Current	<u>v. * </u>	-0.8	0.1	0.8	μΑ
PSRR	Power Supply Rejection Ratio	DO	52	57		dB
A _{OL}	Open Loop Gain	., \	68	78		dB
I _S	Supply Current			4.2	5.2	mA
Disable Chara	cteristics (CLC1015)					
T _{ON}	Turn On Time			150		ns
T _{OFF}	Turn Off Time			25		ns
OFF _{ISO}	Off Isolation	5MHz, $R_L = 100Ω$		75		dB
I _{SD}	Disable Supply Current	DIS tied to GND		127	170	μA
Input Characte	eristics					
R _{IN}	Input Resistance			4.3		ΜΩ
C _{IN}	Input Capacitance			1.8		pF
CMIR	Common Mode Input Range			-0.3 to 3.8		V
CMRR	Common Mode Rejection Ratio	DC, $V_{CM} = 0$ to $V_S - 1.5V$	72	87		dB

Electrical Characteristics at +5V Continued

 $T_A = 25^{\circ}C$, $V_S = +5V$, $R_f = 2k\Omega$, $R_L = 2k\Omega$ to $V_S/2$; G = 2; unless otherwise noted.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
Output Cha	Output Characteristics					
V _{OUT}		$R_L = 10k\Omega$ to $V_S/2$		0.027 to 4.97		V
	Output Swing	$R_L = 2k\Omega$ to $V_S/2$		0.036 to 4.953		V
		$R_L = 150\Omega$ to $V_S/2$	0.3	0.12 to 4.8	4.625	V
	Output Comment			±55		mA
IOUT	Output Current	-40°C to +85°C		±50		mA
I _{SC}	Short Circuit Current	$V_{OUT} = V_S/2$		±85		mA
Vs	Power Supply Operating Range	113.00	2.5	5	5.5	V

Notes:

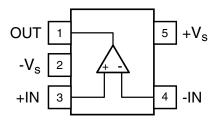
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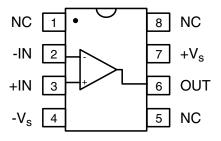
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^{1.} $R_f = 1k\Omega$ was used for optimal performance. (For G = +1, $R_f = 0$)

CLC1005 Pin Configurations TSOT-5



SOIC-8



CLC1005 Pin Assignments

TSOT-5

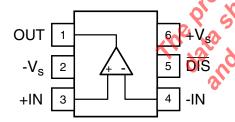
Pin No.	Pin Name	Description
1	OUT	Output
2	-V _S	Negative supply
3	+IN	Positive input
4	-IN	Negative input
5	+V _S	Positive supply

SOIC-8

Pin No.	Pin Name	Description
1	NC	No Connect
2	-IN	Negative input
3	C+IN	Positive input
4	-Vs	Negative supply
5	NC	No Connect
6	ОИТ	Output
7	c+V _S	Positive supply
48 10	NC	No Connect

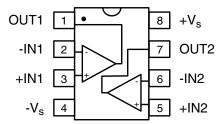
CLC1015 Pin Configurations

TSOT-6



6 OUT	5	NC	No Connect
5 NC	6	OUT	Output
	7	+V _S	Positive supply
	48 0	NC	No Connect
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ations of the state of the stat	CLC1015 TSOT-6	Pin Assignm	nents
ntions of the state of the stat	TSOT-6 Pin No.	Pin Assignm Pin Name	Description
itions	TSOT-6 Pin No.	_	
	CLC1015 TSOT-6 Pin No. 1 2	Pin Name	Description
tions 604Veo Inoline 5 DIS	CLC1015 TSOT-6 Pin No. 1 2 3	Pin Name OUT	Description Output
5 DIS		Pin Name OUT -V _S	Description Output Negative supply
	3	Pin Name OUT -V _S +IN	Description Output Negative supply Positive input

CLC2005 Pin Configuration SOIC-8 / MSOP-8



CLC2005 Pin Assignments

SOIC-8 / MSOP-8

Pin No.	Pin Name	Description
1	OUT1	Output, channel 1
2	-IN1	Negative input, channel 1
3	+IN1	Positive input, channel 1
4	-V _S	Negative supply
5	+IN2	Positive input, channel 2
6	-IN2	Negative input, channel 2
7	OUT2	Output, channel 2
8	+V _S	Positive supply

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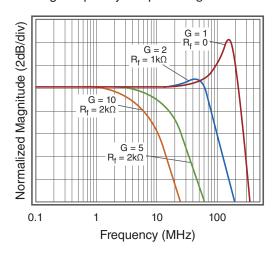
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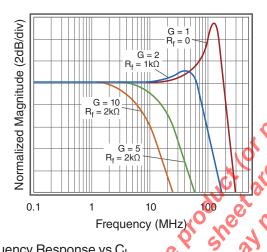
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 $T_A = 25$ °C, $V_S = +5V$, $R_L = 2k\Omega$ to $V_S/2$, G = +2, $R_F = 2k\Omega$; unless otherwise noted.

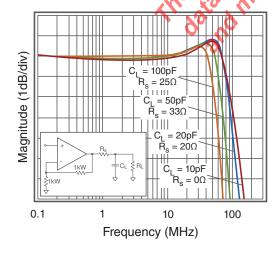
Non-Inverting Frequency Response $V_S = +5V$



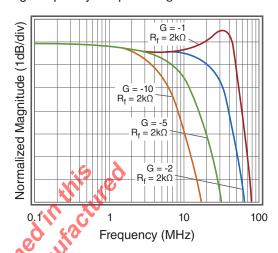
Non-Inverting Frequency Response $V_S = +2.7V$

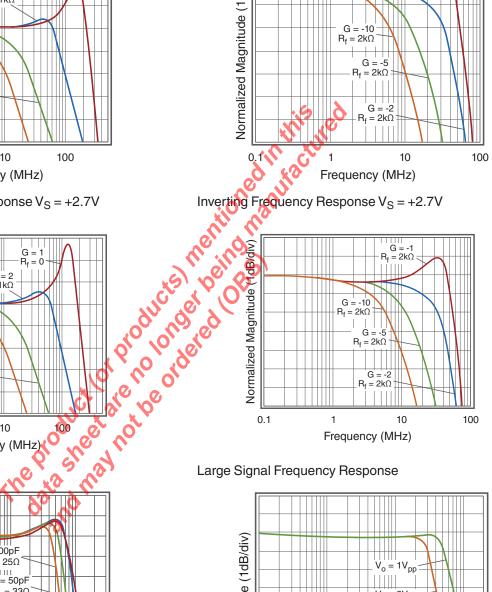


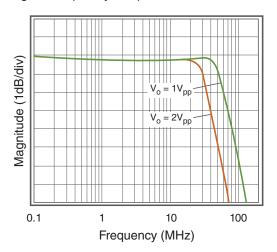
Frequency Response vs CL



Inverting Frequency Response $V_S = +5V$

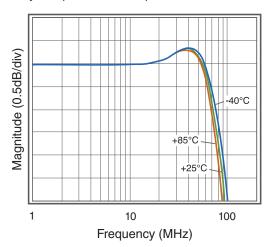




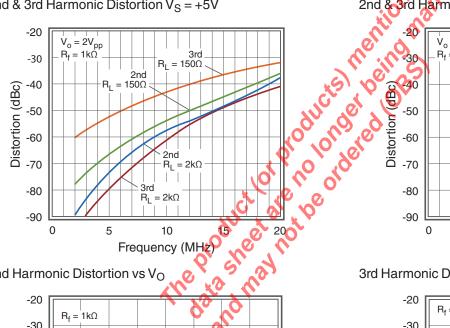


 $T_A = 25^{\circ}C$, $V_S = +5V$, $R_L = 2k\Omega$ to $V_S/2$, G = +2, $R_F = 2k\Omega$; unless otherwise noted.

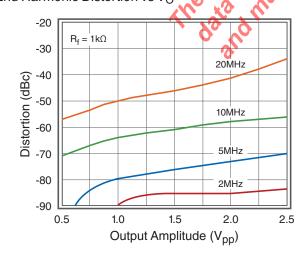
Frequency Response vs. Temperature



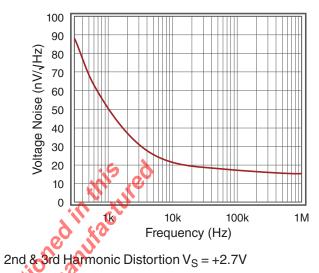
2nd & 3rd Harmonic Distortion $V_S = +5V$

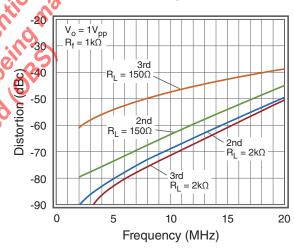


2nd Harmonic Distortion vs VO

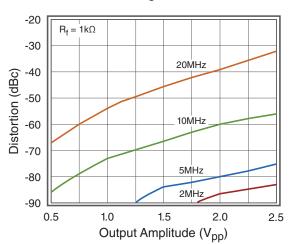


Input Voltage Noise vs Frequency

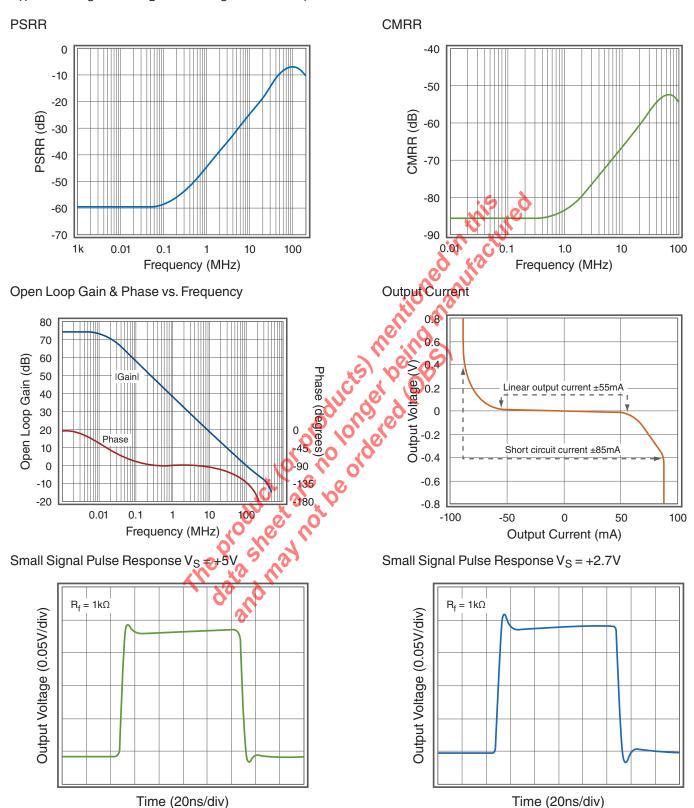




3rd Harmonic Distortion vs VO

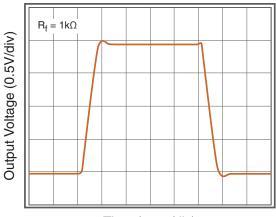


 $T_A = 25^{\circ}C$, $V_S = +5V$, $R_L = 2k\Omega$ to $V_S/2$, G = +2, $R_F = 2k\Omega$; unless otherwise noted.



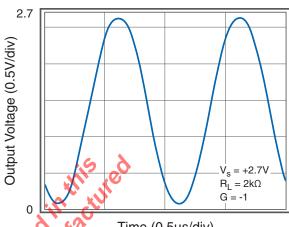
 $T_A = 25$ °C, $V_S = +5V$, $R_L = 2k\Omega$ to $V_S/2$, G = +2, $R_F = 2k\Omega$; unless otherwise noted.

Large Signal Pulse Response V_S = +5V

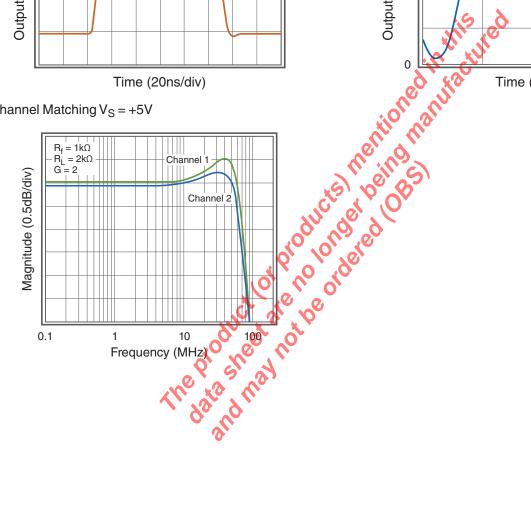


Channel Matching V_S = +5V





Time (0.5µs/div)



Application Information

General Description

The CLC1005, CLC1015, and CLC2005 are single supply. general purpose, voltage-feedback amplifiers fabricated on a complementary bipolar process using a patented topography. They feature a rail-to-rail output stage and are unity gain stable. Both gain bandwidth and slew rate are insensitive to temperature.

The common mode input range extends to 300mV below ground and to 1.2V below Vs. Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct. The output will stay at the rail during this overdrive condition.

The design is short circuit protected and offers "soft" saturation protection that improves recovery time.

Figures 1, 2, and 3 illustrate typical circuit configurations for non-inverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations. Figure 4 shows the typical non-inverting gain circuit for single supply applications.

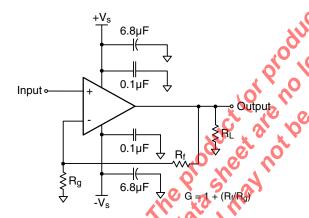


Figure 1: Typical Non-Inverting Gain Circuit

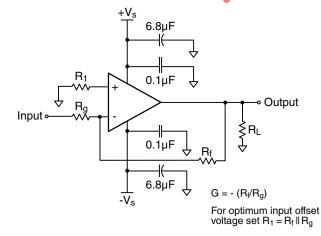


Figure 2: Typical Inverting Gain Circuit

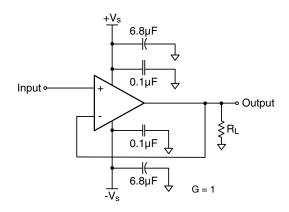


Figure 3: Unity Gain Circuit

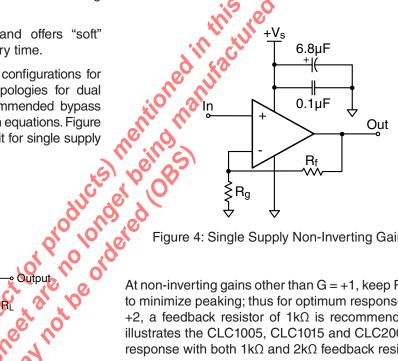


Figure 4: Single Supply Non-Inverting Gain Circuit

At non-inverting gains other than G = +1, keep R_{α} below $1k\Omega$ to minimize peaking; thus for optimum response at a gain of +2, a feedback resistor of $1k\Omega$ is recommended. Figure 5 illustrates the CLC1005, CLC1015 and CLC2005 frequency response with both $1k\Omega$ and $2k\Omega$ feedback resistors.

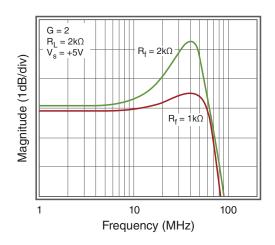


Figure 5: Frequency Response vs. Rf

Overdrive Recovery

For an amplifier, an overdrive condition occurs when the output and/or input ranges are exceeded. The recovery time varies based on whether the input or output is overdriven and by how much the ranges are exceeded. The CLC1005, CLC1015, and CLC2005 will typically recover in less than 20ns from an overdrive condition. Figure 6 shows the CLC2005 in an overdriven condition.

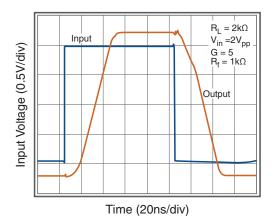


Figure 6: Overdrive Recovery

Enable/Disable Function

The CLC1015 offers an active-low disable pin that can be used to lower its supply current. Leave the pin floating to enable to part. Pull the disable pin to the negative supply (which is ground in a single supply application) to disable the output. During the disable condition, the nominal supply current will drop below 127µA and the output will be at a high impedance with about 2pF capacitance.

Power Dissipation

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Power dissipation should not be a factor when operating under the stated $2k\Omega$ load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond it's intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value Theta, IA (θ_{JA}) is used along with the total die power dissipation.

$$T_{Junction} = T_{Ambient} + (\theta_{JA} \times P_D)$$

Where T_{Ambient} is the temperature of the working environment.

In order to determine PD, the power dissipated in the load

needs to be subtracted from the total power delivered by the supplies.

Supply power is calculated by the standard power equation.

$$P_{\text{supply}} = V_{\text{supply}} \times I_{\text{RMSsupply}}$$

 $V_{\text{supply}} = V_{\text{S+}} - V_{\text{S-}}$

Power delivered to a purely resistive load is:

$$P_{load} = ((V_{load})_{RMS^2})/Rload_{eff}$$

The effective load resistor (Rloadeff) will need to include the effect of the feedback network. For instance,

Rload $_{eff}$ in Figure 3 would be calculated as: $R_L \parallel (R_f + R_g)$

$$R_{l} \parallel (R_{f} + R_{d})$$

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here, PD can be found from

Quiescent power can be derived from the specified I_S values along with known supply voltage, V_{supply}. Load power can be calculated as above with the desired signal amplitudes using:

$$(V_{load})_{RMS} = V_{peak} / \sqrt{2}$$

$$(I_{load})_{RMS} = (V_{load})_{RMS} / Rload_{eff}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

$$P_{Dynamic} = (V_{S+} - V_{load})_{RMS} \times (I_{load})_{RMS}$$

Assuming the load is referenced in the middle of the power rails or V_{supply}/2.

The CLC1015 is short circuit protected. However, this may not guarantee that the maximum junction temperature (+150°C) is not exceeded under all conditions. Figure 7 shows the maximum safe power dissipation in the package vs. the ambient temperature for the packages available.

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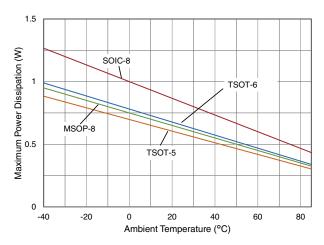


Figure 7. Maximum Power Derating

Driving Capacitive Loads

Increased phase delay at the output due to capacitive loading can cause ringing, peaking in the frequency response, and possible unstable behavior. Use a series resistance, R_S , between the amplifier and the load to help improve stability and settling performance. Refer to Figure 8.

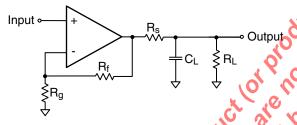


Figure 8. Addition of R_S for Driving Capacitive Loads

Table 1 provides the recommended R_S for various capacitive loads. The recommended R_S values result in approximately <1dB peaking in the frequency response.

C _L (pF)	R _S (Ω)	-3dB BW (MHz)
22pF	0	118
47pF	15	112
100pF	15	91
492pF	6.5	59

Table 1: Recommended R_S vs. C_L

For a given load capacitance, adjust R_S to optimize the tradeoff between settling time and bandwidth. In general, reducing R_S will increase bandwidth at the expense of additional overshoot and ringing.

Layout Considerations

General layout and supply bypassing play major roles in high frequency performance. Exar has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

- Include 6.8µF and 0.1µF ceramic capacitors for power supply decoupling
- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.1µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts below for more information.

Evaluation Board Information

The following evaluation boards are available to aid in the testing and layout of these devices:

Evaluation Board #	Products			
CEB002	CLC1005 and CLC1015 in TSOT			
CEB003	CLC1005 in SOIC			
CEB006	CLC2005 in SOIC			
CEB010	CLC2005 in MSOP			

Evaluation Board Schematics

Evaluation board schematics and layouts are shown in Figures 9-18. These evaluation boards are built for dual-supply operation. Follow these steps to use the board in a single-supply application:

- 1. Short -V_S to ground.
- Use C3 and C4, if the -V_S pin of the amplifier is not directly connected to the ground plane.

exar.com/CLC1005

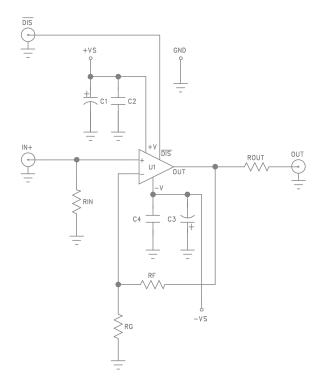


Figure 9. CEB002 and CEB003 Schematic

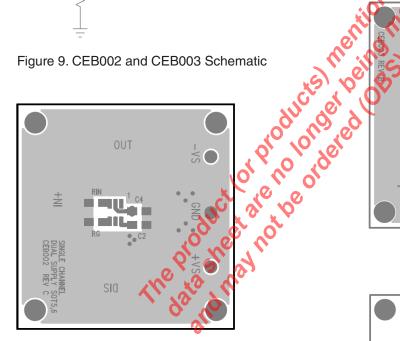


Figure 10. CEB002 Top View

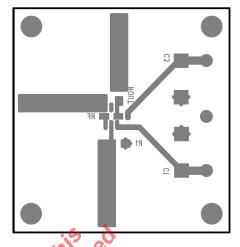


Figure 11. CEB002 Bottom View

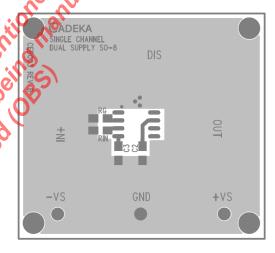


Figure 12. CEB003 Top View

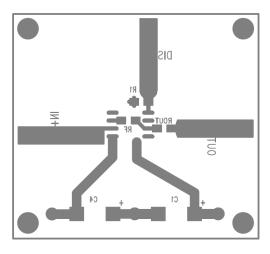


Figure 13. CEB003 Bottom View

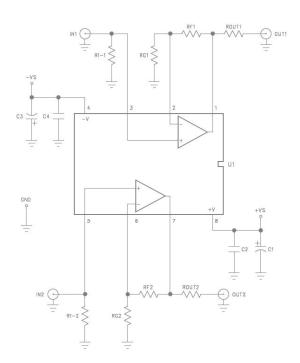


Figure 14. CEB006 & CEB010 Schematic

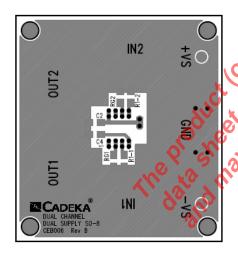


Figure 15. CEB006 Top View

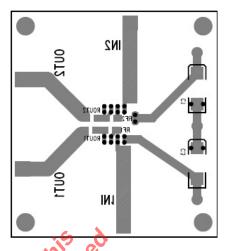


Figure 16. CEB006 Bottom View

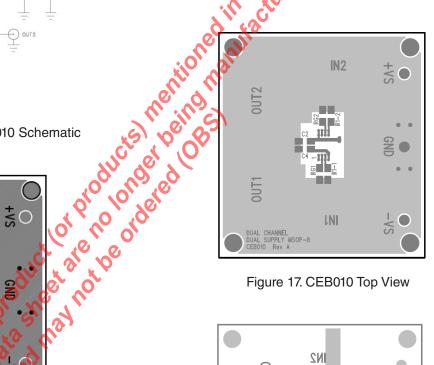


Figure 17. CEB010 Top View

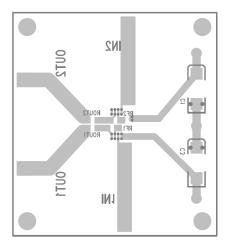
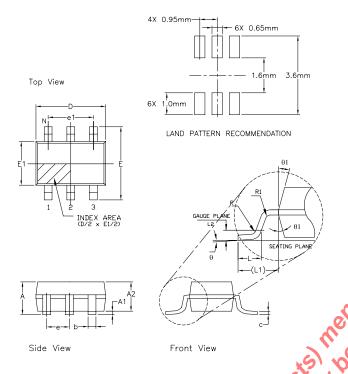


Figure 18. CEB010 Bottom View

Mechanical Dimensions

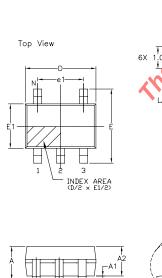
TSOT-6 Package

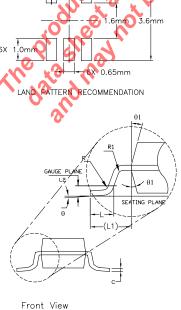


4X 0.95mm

6 PIN TSOT (OPTION 2)							
SYMBOLS	DIMENSION IN MM (Control Unit)				ISION IN INCH erence Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX	
Α	0.75	_	0.80	0.030	_	0.031	
A1	0.00	_	0.05	0.000	_	0.002	
A2	0.70	0.75	0.78	0.028	0.036	0.031	
b	0.35	_	0.50	0.012	_	0.020	
С	0.10	_	0.20	0.003	_	0.008	
D	2.90 BSC			0.114 BSC			
E	2.80 BSC			0.110 BSC			
E1 🍫	1.60 BSC			0.063 BSC			
ę 🚺	0.95 BSC			0.038 BSC			
e1	1.90 BSC			С	.075 B	SC	
C	0.37	0.45	0.60	0.012	0.018	0.024	
L1		0.60 REF			.024 RE	F	
L2	0.25 BSC			0.	.010 BS	SC SC	
R	0.10 —		_	0.004	_	_	
R1	0.10	_	0.25	0.004	_	0.010	
θ	0,	4*	8*	0,	4*	8*	
θ1	4*	10*	12*	4°	10°	12*	
N	6				6		

TSOT-5 Package





5 Pin TSOT (OPTION 2)						
SYMBOLS	DIMENSION IN MM (Control Unit)			DIMENSION IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
Α	0.75	_	0.80	0.030	_	0.031
A1	0.00	_	0.05	0.000	_	0.002
A2	0.70	0.75	0.78	0.028	0.030	0.031
ь	0.35	_	0.50	0.012	_	0.020
С	0.10	_	0.20	0.003	_	0.008
D	2.90 BSC			0.114 BSC		
E	2.80 BSC			0.110 BSC		
E1	1.60 BSC			0.063 BSC		
е	0.95 BSC			0.038 BSC		
e1	1.90 BSC			0.075 BSC		
L	0.37	0.45	0.60	0.012	0.018	0.024
L1	0.60 REF			0.024 REF		
L2	0.25 BSC			0.010 BSC		
R	0.10	_	_	0.004	_	_
R1	0.10	_	0.25	0.004	_	0.010
θ	0,	4*	8,	0,	4.	8*
θ1	4.	10°	12*	4.	10°	12*
N	5				5	

Side View

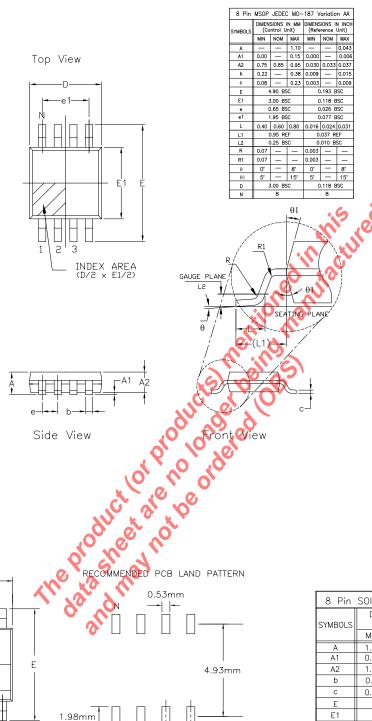
MSOP-8 Package

SOIC-8 Package

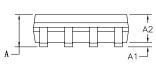
Ε1

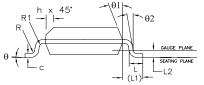
INDEX AREA (D/2 X E1/2)

Top View



8 Pin	8 Pin SOICN JEDEC MS-012 Variation AA					
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
Α	1.35	-	1.75	0.053	_	0.069
A1	0.10	_	0.25	0.004	_	0.010
A2	1.25	_	1.65	0.049	_	0.065
b	0.31	_	0.51	0.012	_	0.020
С	0.17	_	0.25	0.007	_	0.010
Ε	6.00 BSC			0.236 BSC		
E1	3.90 BSC			0.154 BSC		
е	1.27 BSC			0.050 BSC		
h	0.25	_	0.50	0.010	_	0.020
L	0.40	_	1.27	0.016	_	0.050
L1	1.04 REF			0.041 REF		
L2	0.25 BSC				.010 BS0	2
R	0.07	_	_	0.003	_	_
R1	0.07	_	_	0.003	_	_
θ	0,		8°	0,	_	8*
θ1	5°	_	15°	5°	_	15°
θ2	0,	_	_	0,	_	
D	4.90 BSC			0	.193 BS	С
N	8				8	





1.27mm

Side View Front View

Ordering Information

Part Number	Package	Green	Operating Temperature Range	Packaging			
CLC1005 Ordering Information	CLC1005 Ordering Information						
CLC1005IST5X	TSOT-5	Yes	-40°C to +85°C	Tape & Reel			
CLC1005IST5MTR	TSOT-5	Yes	-40°C to +85°C	Mini Tape & Reel			
CLC1005IST5EVB	Evaluation Board	N/A	N/A	N/A			
CLC1005ISO8X	SOIC-8	Yes	-40°C to +85°C	Tape & Reel			
CLC1005ISO8MTR	SOIC-8	Yes	-40°C to +85°C	Mini Tape & Reel			
CLC1005ISO8EVB	Evaluation Board	N/A	N/A	N/A			
CLC1015 Ordering Information							
CLC1015IST6X	TSOT-6	Yes	-40°C to +85°C	Tape & Reel			
CLC1015IST6MTR	TSOT-6	Yes	-40°C to +85°C	Mini Tape & Reel			
CLC1015IST6EVB	Evaluation Board	N/A	N/A	N/A			
CLC2005 Ordering Information							
CLC2005ISO8X	SOIC-8	Yes	7-40°C to +85°C	Tape & Reel			
CLC2005ISO8MTR	SOIC-8	Yes	-40°C to +85°C	Mini Tape & Reel			
CLC2005ISO8EVB	Evaluation Board	N/A	N/A	N/A			
CLC2005IMP8X	MSOP-8	Yes	-40°C to +85°C	Tape & Reel			
CLC2005IMP8MTR	MSOP-8	Yes	-40°C to +85°C	Mini Tape & Reel			
CLC2005IMP8EVB	Evaluation Board	N/A	N/A	N/A			

Moisture sensitivity level for all parts is MSL-1. Mini tape and reel quantity is 250

Revision History

Revision	Date	Description
2D (ECN 1513-01)	March 2015	Reformat into Exar data sheet template. Updated ordering information table to include MTR and EVB part numbers. Updated thermal resistance numbers and package outline drawings. Added CLC1015 back into data sheet.

For Further Assistance:

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