

APRIL 6, 2021 REV. 1.0.5

#### GENERAL DESCRIPTION

The XRT86VL30 is a single channel T1/E1/J1 BITS clock recovery element and framer and LIU integrated solution featuring R<sup>3</sup> technology (Relayless, Reconfigurable, Redundancy). The physical interface is optimized with internal impedance, and with the patented pad structure, the XRT86VL30 provides protection from power failures and hot swapping.

The XRT86VL30 contains an integrated DS1/E1/J1 framer and LIU which provides DS1/E1/J1 framing and error accumulation in accordance with ANSI/ITU\_T specifications. The framer has its own framing synchronizer and transmit-receive slip buffers. The slip buffers can be independently enabled or disabled as required and can be configured to frame to the common DS1/E1/J1 signal formats.

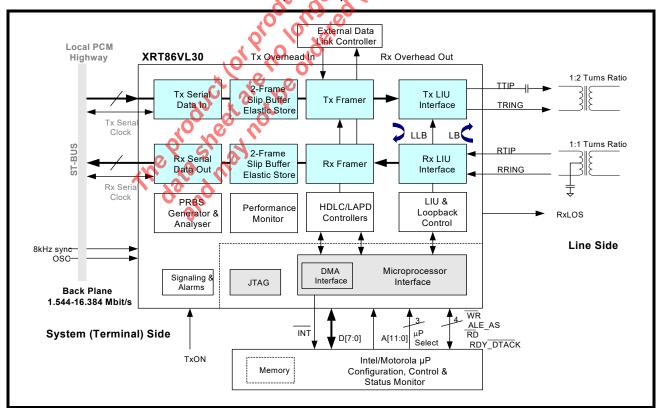
The Framer block contains its own Transmit and Receive T1/E1/J1 Framing function. There are 3 Transmit HDLC controllers which encapsulate contents of the Transmit HDLC buffers into LAPD Message frames. There are 3 Receive HDLC controllers which extract the payload content of

Receive LAPD Message frames from the incoming T1/E1/J1 data stream and write the contents into the Receive HDLC buffers. The framer also contains a Transmit and Overhead Data Input port, which permits Data Link Terminal Equipment direct access to the outbound T1/E1/J1 frames. Likewise, a Receive Overhead output data port permits Data Link Terminal Equipment direct access to the Data Link bits of the inbound T1/E1/J1 frames.

The XRT86VL30 fully meets all of the latest T1/E1/J1 specifications: ANSI T1.101-1999, ANSI T1/E1.107-1988, ANSI T1/E1.403-1995, ANSI T1/E1.231-1993, ANSI T1/E1.408-1990, AT&T TR 62411 (12-90) TR54016, and JTU G.703 (Including Section 13 - Synchronization), G.704, G706 and G.733, AT&T Pub. 43801, and ETS 300 011, 300 233, JT G.703, JT G.704, JT G706, J.431. Extensive test and diagnostic functions include Loop-backs, Boundary scan, Pseudo Random bit sequence (PRBS) test pattern generation, Performance Monitor, Bit Error Rate (BER) meter, forced error insertion, and LAPD unchannelized data payload processing according to ITU-T standard Q.921.

# APPLICATIONS AND FEATURES (NEXT PAGE)

FIGURE 1. XRT86VL30 SINGLE CHANNEL DS1 (17/E11/11) FRAMER/LIU COMBO



#### XRT86VL30

#### T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL



REV. 1.0.5

#### **APPLICATIONS**

- BITS Timing
- High-Density T1/E1/J1 interfaces for Multiplexers, Switches, LAN Routers and Digital Modems
- SONET/SDH terminal or Add/Drop multiplexers (ADMs)
- T1/E1/J1 add/drop multiplexers (MUX)
- Channel Service Units (CSUs): T1/E1/J1 and Fractional T1/E1/J1
- Digital Access Cross-connect System (DACs)
- Digital Cross-connect Systems (DCS)
- Frame Relay Switches and Access Devices (FRADS)
- ISDN Primary Rate Interfaces (PRA)
- PBXs and PCM channel bank
- T3 channelized access concentrators and M13 MUX
- Wireless base stations
- ATM equipment with integrated DS1 interfaces
- Multichannel DS1 Test Equipment
- T1/E1/J1 Performance Monitoring
- Voice over packet gateways
- Routers

#### **FEATURES**

- Supports Section 13 Synchronization Interface in ITU 6.703 for both Transmit and Receive Paths
- Supports SSM Synchronous Messaging Generation (BOC for T1, National Bits for E1) on the Transmit Path
- Supports SSM Synchronous Messaging Extraction (BOC for T1, National Bits for E1) on the Receive Path
- Supports BITS timing generation on the Transmit Outputs
- Supports BITS timing extraction from NRZ data on the Analog Receive Path
- Parallel Microcontroller Interface
- Independent, full duplex DS1 Tx and Rx Framer/LIUs
- Two 512-bit (two-frame) elastic store, PCM frame slip buffers (FIFO) on TX and Rx provide up to 8.192 MHz asynchronous back plane connections with jitter and wander attenuation
- Supports input PCM and signaling data at 1.544, 2.048, 4.096 and 8.192 Mbits. Also supports 2-channel multiplexed 12.352/16.384 (HMVIP/H.100) Mbit/s on the back plane bus
- Programmable output clocks for Fractional T1/E1/J1
- Supports Channel Associated Signaling (CAS)
- Supports Common Channel Signalling (CCS)
- Supports ISDN Primary Rate Interface (ISDN PRI) signaling
- Extracts and inserts robbed bit signaling (RBS)
- 3 Integrated HDLC controllers for transmit and receive, each controller having two 96-byte buffers (buffer 0 / buffer 1)
- HDLC Controllers Support SS7



- Timeslot assignable HDLC
- V5.1 or V5.2 Interface
- Automatic Performance Report Generation (PMON Status) can be inserted into the transmit LAPD interface every 1 second or for a single transmission
- Supports SPRM and NPRM
- Alarm Indication Signal with Customer Installation signature (AIS-CI)
- Remote Alarm Indication with Customer Installation (RAI-CI)
- Gapped Clock interface mode for Transmit and Receive.
- Intel/Motorola or Power PC interfaces for configuration, control and status monitoring
- Parallel search algorithm for fast frame synchronization
- Wide choice of T1 framing structures: SF/D4, ESF, SLC®96, T1DM and N-Frame (non-signaling)
- Direct access to D and E channels for fast transmission of data link information
- Full BERT Controller for generation and detection on system and line side of the chip.
- PRBS, QRSS, and Network Loop Code generation and detection.
- Three Independent, simultaneous Loop Code Detectors per Channel
- Programmable Interrupt output pin
- Supports programmed I/O and DMA modes of Read-Write access
- The framer block encodes and decodes the T1/E1/J1 Frame serial data
- Detects and forces Red (SAI), Yellow (RAI) and Blue (AIS) Alarms
- Detects OOF, LOF, LOS errors and COFA conditions
- Loopbacks: Local (LLB) and Line remote (LB)
- Facilitates Inverse Multiplexing for ATM
- Performance monitor with one second polling
- Boundary scan (IEEE 1149.1) JTAG test port
- Accepts external 8kHz Sync reference
- 1.8V Inner Core
- 3.3V CMOS operation with 5V tolerant inputs
- 80-pin LQFP and 128-pin LQFP package options with -40°C to +85°C operation

#### ORDERING INFORMATION

PART NUMBER	PACKAGE	OPERATING TEMPERATURE RANGE
XRT86VL30IV-F	128 Pin LQFP(14x20x1.4mm)	-40°C to +85°C
XRT86VL30IV80-F	80 Pin LQFP(12x12x1.4mm)	-40°C to +85°C



# **LIST OF FIGURES**

Figure 1.: XRT86VL30 2-channel DS1 (T1/E1/J1) Framer/LIU Combo	1
Figure 2.: Framer System Transmit Timing Diagram (Base Rate/Non-Mux)	
Figure 3.: Framer System Receive Timing Diagram (RxSERCLK as an Output)	
Figure 4.: Framer System Receive Timing Diagram (RxSERCLK as an Input)	
Figure 5.: Framer System Transmit Timing Diagram (HMVIP and H100 Mode)	
Figure 6.: Framer System Receive Timing Diagram (HMVIP/H100 Mode)	
Figure 7.: Framer System Transmit Overhead Timing Diagram	
Figure 8.: Framer System Receive Overhead Timing Diagram (RxSERCLK as an Output)	
Figure 9.: Framer System Receive Overhead Timing Diagram (RxSERCLK as an Input)	
Figure 10.: ITU G.703 Pulse Template	. 54
Figure 11.: DSX-1 Pulse Template (normalized amplitude)	
Figure 13.: Intel μP Interface Timing During Programmed I/O Read and Write Operations When ALE Is Tied 'HIGH'.	
Figure 14.: Motorola Asychronous Mode Interface Signals During Programmed I/O Read and Write Operations	
Figure 15.: Power PC 403 Interface Signals During Programmed I/O Read and Write Operations	. 60
Figure 13: Intel µP Interface I Iming During Programmed I/O Read and Write Operations When ALE Is Tied 'HIGH' Figure 13: Intel µP Interface Timing During Programmed I/O Read and Write Operations When ALE Is Tied 'HIGH' Figure 14: Motorola Asychronous Mode Interface Signals During Programmed I/O Read and Write Operations Figure 15: Power PC 403 Interface Signals During Programmed I/O Read and Write Operations	





# LIST OF TABLES

Table 1:: List by Pin Number	
Table 2:: Pin Types	
Table 3:: Pin Description Structure	
Table 4:: XRT86VL30 Power Consumption	42
Table 5:: E1 Receiver Electrical Characteristics	50
Table 6:: T1 Receiver Electrical Characteristics	51
Table 7:: E1 Transmitter Electrical Characteristics	52
Table 8:: E1 Transmit Return Loss Requirement	
Table 9:: T1 Transmitter Electrical Characteristics	53
Table 10:: Transmit Pulse Mask Specification	
Table 11:: DSX1 Interface Isolated pulse mask and corner points	
Table 12:: AC Electrical Characteristics	
Table 13:: Intel Microprocessor Interface Timing Specifications	
Table 14:: Intel Microprocessor Interface Timing Specifications	58
Table 15:: Motorola Asychronous Mode Microprocessor Interface Timing Specifications	59
Table 14:: Intel Microprocessor Interface Timing Specifications  Table 15:: Motorola Asychronous Mode Microprocessor Interface Timing Specifications  Table 16:: Power PC 403 Microprocessor Interface Timing Specifications  Table 16:: Power PC 403 Microprocessor Interface Timing Specifications  Table 16:: Power PC 403 Microprocessor Interface Timing Specifications	

# T1/E1/J1 BITS ELEMENT -



REV. 1.0.5

1.0 128-PIN LIST

# TABLE 1: 128-PIN LIST BY PIN NUMBER

PIN         PIN NAME           1         LOP           2         DVDD3v3           3         NC           4         DVDD1v8           5         DGND           6         TRING           7         TVDD3v3           8         TTIP           9         TGND           10         JTAG_RING           11         JTAG_TIP           12         RGND           13         RRING           14         RTIP           15         RVDD3v3           16         AVDD1v8           17         AGND           18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKnOUT           26         RXOH           27         RXCHN4           28         RXCHN3           29         DGND           30         RXCASYNC           31         RXOHCLK	PIN NUMBER		
2 DVDD3v3 3 NC 4 DVDD1v8 5 DGND 6 TRING 7 TVDD3v3 8 TTIP 9 TGND 10 JTAG_RING 11 JTAG_TIP 12 RGND 13 RRING 14 RTIP 15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RXOH 27 RXCHN4 28 RXCHN3 29 DGND 30 RXCASYNC	Pin	PIN NAME	
3         NC           4         DVDD1v8           5         DGND           6         TRING           7         TVDD3v3           8         TTIP           9         TGND           10         JTAG_RING           11         JTAG_TIP           12         RGND           13         RRING           14         RTIP           15         RVDD3v3           16         AVDD1v8           17         AGND           18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKOUT           26         RXOH           27         RXCHN4           28         RXCHN3           29         DGND           30         RXCASYNC	1	LOP	
4 DVDD1v8 5 DGND 6 TRING 7 TVDD3v3 8 TTIP 9 TGND 10 JTAG_RING 11 JTAG_TIP 12 RGND 13 RRING 14 RTIP 15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RXOH 27 RXCHN4 28 RXCHN3 29 DGND 30 RXCASYNC	2	DVDD3v3	
5         DGND           6         TRING           7         TVDD3v3           8         TTIP           9         TGND           10         JTAG_RING           11         JTAG_TIP           12         RGND           13         RRING           14         RTIP           15         RVDD3v3           16         AVDD1v8           17         AGND           18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKNOUT           26         RXOH           27         RXCHN4           28         RXCHN3           29         DGND           30         RXCASYNC	3	NC	
6 TRING 7 TVDD3v3 8 TTIP 9 TGND 10 JTAG_RING 11 JTAG_TIP 12 RGND 13 RRING 14 RTIP 15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RXOH 27 RXCHN4 28 RXCHN3 29 DGND 30 RXCASYNC	4	DVDD1v8	
7 TVDD3v3  8 TTIP  9 TGND  10 JTAG_RING  11 JTAG_TIP  12 RGND  13 RRING  14 RTIP  15 RVDD3v3  16 AVDD1v8  17 AGND  18 SENSE  19 ANALOG  20 VDDPLL1v8  21 VDDPLL1v8  22 PLLGND  23 PLLGND  24 MCLKIN  25 MCLKnOUT  26 RXOH  27 RXCHN4  28 RXCHN3  29 DGND  30 RXCASYNC	5	DGND	
8         TTIP           9         TGND           10         JTAG_RING           11         JTAG_TIP           12         RGND           13         RRING           14         RTIP           15         RVDD3v3           16         AVDD1v8           17         AGND           18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKNOUT           26         RXOH           27         RXCHN4           28         RXCHN3           29         DGND           30         RXCASYNC	6	TRING	
9 TGND 10 JTAG_RING 11 JTAG_TIP 12 RGND 13 RRING 14 RTIP 15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RXOH 27 RXCHN4 28 RXCHN3 29 DGND 30 RXCASYNC	7	TVDD3v3	
10 JTAG_RING 11 JTAG_TIP 12 RGND 13 RRING 14 RTIP 15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RXOH 27 RXCHN4 28 RXCHN3 29 DGND 30 RXCASYNC	8	TTIP	
11 JTAG_TIP  12 RGND  13 RRING  14 RTIP  15 RVDD3v3  16 AVDD1v8  17 AGND  18 SENSE  19 ANALOG  20 VDDPLL1v8  21 VDDPLL1v8  22 PLLGND  23 PLLGND  24 MCLKIN  25 MCLKnOUT  26 RXOH  27 RXCHN4  28 RXCHN3  29 DGND  30 RXCASYNC	9	TGND	
12 RGND 13 RRING 14 RTIP 15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RXOH 27 RXCHN4 28 RXCHN3 29 DGND 30 RXCASYNC	10	JTAG_RING	
13         RRING           14         RTIP           15         RVDD3v3           16         AVDD1v8           17         AGND           18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKnOUT           26         RxOH           27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	11	JTAG_TIP	
14         RTIP           15         RVDD3v3           16         AVDD1v8           17         AGND           18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKnOUT           26         RxOH           27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	12	RGND	
15 RVDD3v3 16 AVDD1v8 17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RxOH 27 RxCHN4 28 RxCHN3 29 DGND 30 RxCASYNC	13	RRING	
16       AVDD1v8         17       AGND         18       SENSE         19       ANALOG         20       VDDPLL1v8         21       VDDPLL1v8         22       PLLGND         23       PLLGND         24       MCLKIN         25       MCLKnOUT         26       RxOH         27       RxCHN4         28       RxCHN3         29       DGND         30       RxCASYNC	14	RTIP	
17 AGND 18 SENSE 19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RxOH 27 RxCHN4 28 RxCHN3 29 DGND 30 RxCASYNC	15	RVDD3v3	
18         SENSE           19         ANALOG           20         VDDPLL1v8           21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKnOUT           26         RxOH           27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	16	AVDD1v8	
19 ANALOG 20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RxOH 27 RxCHN4 28 RxCHN3 29 DGND 30 RxCASYNC	17	AGND	
20 VDDPLL1v8 21 VDDPLL1v8 22 PLLGND 23 PLLGND 24 MCLKIN 25 MCLKnOUT 26 RxOH 27 RxCHN4 28 RxCHN3 29 DGND 30 RxCASYNC	18	SENSE	
21         VDDPLL1v8           22         PLLGND           23         PLLGND           24         MCLKIN           25         MCLKnOUT           26         RxOH           27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	19	ANALOG	
22       PLLGND         23       PLLGND         24       MCLKIN         25       MCLKnOUT         26       RxOH         27       RxCHN4         28       RxCHN3         29       DGND         30       RxCASYNC	20	VDDPLL1v8	
23 PLLGND  24 MCLKIN  25 MCLKnOUT  26 RXOH  27 RXCHN4  28 RXCHN3  29 DGND  30 RXCASYNC	21	VDDPLL1v8	
24         MCLKIN           25         MCLKnOUT           26         RxOH           27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	22	PLLGND	
25 MCLKnOUT 26 RxOH 27 RxCHN4 28 RxCHN3 29 DGND 30 RxCASYNC	23	PLLGND	
26         RxOH           27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	24	MCLKIN	
27         RxCHN4           28         RxCHN3           29         DGND           30         RxCASYNC	25	MCLKnOUT	
28 RxCHN3 29 DGND 30 RxCASYNC	26	RxOH	
29 DGND 30 RxCASYNC	27	RxCHN4	
30 RxCASYNC	28	RxCHN3	
	29	DGND	
31 RxOHCLK	30	RxCASYNC	
	31	RxOHCLK	

HARDWARE MANUAL		
Pin	PIN NAME	
32	RxCHN2	
33	RxSYNC	
34	NC	
35	NC	
36	RxCH1	
37	DVDD3v3	
38	RxCHCLK	
39	RxCRCSYNC	
40	RxCHN0	
41	DVDD1v8	
42	RxSERCLK	
43	RxLOS	
44	RxSER	
45	TxCHN4	
46	TxCHN3	
47	TxCHN2	
48	DGND	
49	TxCHCLK	
50	TxOHN1	
51	TxOH	
52	DVDD3v3	
53	TxCHN0	
<b>2</b> 54	TXSERCLK	
55)	TxSER	
56 7	DVDD1v8	
57	TxOHCLK	
58	TxMSYNC	
59	TxSYNC	
60	DGND	
61	REQ1	
62	ACK0	
63	DVDD1v8	
64	REQ0	

PIN	PIN NAME
65	ACK1
66	NC
67	NC
68	PCLK
69	DATA0
70	DATA1
71	RD
72	DGND
73	DBEN
74	RDY
75	ADDR0
76	ADDR1
77	ADDR2
78	DVDD1v8
79	ADDR3
80	ADDR4
810	ADDR5
82	ADDR6
83	DGND
84	ADDR7
85	RESET
86	OSCCLK
87	DGND
88	8KSYNC
89	ADDR8
90	DATA2
91	DATA3
92	DVDD3v3
93	ALE
94	ADDR9
95	ADDR10
96	ĪNT
97	ADDR11

Pin	PIN NAME
98	NC
99	NC
100	BLAST
101	DATA4
102	DGND
103	DATA5
104	DATA6
105	DVDD1v8
106	DATA7
107	WR
108	CS
109	DGND
110	DGND
111	TCK
112	TRST
113	TDI
114	TMS
115	TDO
116	GPIO1
117	GPIO0
118	GPIO2
119	GPIO3
120	aTEST
121	TEST
122	8KEXTOSC
123	fADDR
124	iADDR
125	PTYPE2
126	PTYPE1
127	PTYPE0
128	TxON



2.0 80-PIN LIST

# TABLE 2: 80-PIN LIST BY PIN NUMBER

Pin	PIN NAME
1	DVDD1v8
2	DGND
3	TRING
4	TVDD3v3
5	TTIP
6	TGND
7	RGND
8	RRING
9	RTIP
10	RVDD3v3
11	AVDD1v8
12	AGND
13	VDDPLL1v8
14	VDDPLL1v8
15	PLLGND
16	PLLGND
17	MCLKIN
18	RxCHN4
19	RxCASYNC

Pin	PIN NAME
20	RxSYNC
21	DVDD3v3
22	RxCRCSYNC
23	DVDD1v8
24	RxSERCLK
25	RxLOS
26	RxSER
27	DGND
28	DVDD3v3
29	TxSERCLK
30	TxSER
31	TxMSYNC
32	TxSYNC
33	DGND
34	REQ1
35	ACK0
36	DVDD1v8
37	REQ0
38	ACK!
39	PCLK
40	DATA0

	Pin	PIN NAME
	41	DATA1
	42	RD
	43	RDY
	44	ADDR0
	45	ADDR1
	46	ADDR2
	47	ADDR3
	48	ADDR4
	49	ADDR5
	50	ADDR6
	51	ADDR7
	52	RESET
	53	ADDR8
2	54	DATA2
	55	DATA3
	56	ALE
	57	ADDR9
	58	ADDR10
	59	ĪNT
	60	ADDR11
	61	DATA4

Pin	PIN NAME
62	DGND
63	DATA5
64	DATA6
65	DVDD1v8
66	DATA7
67	WR
68	CS
69	DGND
70	DGND
71	DGND
72	GPIO1
73	GPIO0
74	GPIO2
75	GPIO3
76	PTYPE2
77	PTYPE1
78	PTYPE0
79	TxON
80	DVDD3v3



#### 3.0 PIN DESCRIPTIONS

There are six types of pins defined throughout this pin description and the corresponding symbol is presented in table below. All output pins are "tri-stated" upon hardware RESET.

**TABLE 3: PIN TYPES** 

SYMBOL	PIN TYPE
I	Input
0	Output
I/O	Bidirectional
GND	Ground
PWR	Power
NC	No Connect

The structure of the pin description is divided into thirteen groups, as presented in the table below

TABLE 4: PIN DESCRIPTION STRUCTURE

Section	PAGE NUMBER
Transmit System Side Interface	page 7
Transmit Overhead Interface	page 15
Receive Overhead Interface	page 17
Receive System Side Interface	page 18
Receive Line Interface	page 26
Transmit Line Interface	page 27
Timing Interface	page 27
JTAG Interface	page 28
Microprocessor Interface	page 29
Power Pins (3.3V)	page 37
Power Pins (1.8V)	page 37
Ground Pins	page 37
No Connect Pins	page 37



SIGNAL NAME	128-Pin#	80-PIN#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxSER/ TxPOS	55	30	- Of the last of t	products not be ordered	Transmit Serial Data Input (TxSER)/Transmit Positive Digital Input (TxPOS):  The exact function of this pin depends on the mode of operation selected, as described below.  DS1/E1 Mode - TxSER  This pin functions as the transmit serial data input on the system side interface, which are latched on the rising edge of the TxSERCLk pin. Any payload data applied to this pin will be inserted into an outbound DS1/E1 frame and output to the line. In DS1 mode, the framing alignment bits, facility data link bits, CRC-6 bits, and signaling information can also be inserted from this input pin if configured appropriately. In E1 mode, all data intended to be transported via Time Slots 1 through 15 and Time slots 17 through 31 must be applied to this input pin. Data intended for Time Slots 0 and 16 can also be applied to this input pin if configured accordingly.  DS1 or E1 High-Speed Multiplexed Mode* - TxSER  In this mode, this pin is used as the high-speed multiplexed data must be applied to TxSER in a byte or bit-interleaved way. The three unused channels are ignored for the single channel device. The framer latches in the multiplexed data on TxSER using TxMSYNC/TxINCLK and demultiplexes this data into 1 serial stream and 3 unused serial streams. The LIU block will then output the data to the line interface using TxSERCLK.  DS1 or E1 Framer Bypass Mode - TxPOS  In this mode, TxSER is used for the positive digital input pin (TxPOS) to the LIU.  Note:  1. *High-speed multiplexed modes include (For T1/E1) 16.384MHz HMVIP, H.100, Bit-multiplexed modes, and (For T1 only) 12.352MHz Bit-multiplexed mode.  2. In DS1 high-speed modes, the DS-0 data is mapped into an E1 frame by ignoring every fourth time slot (don't care).  3. This pin is internally pulled "High".

# EXAR Powering Connectivity

TxLINECLK  (Tx The tion In E This late the input Wh This tim 1.5 tion Wh This the trar cloor rate DS INF In ti Wh Ac	ransmit Serial Clock (TxSERCLK)/Transmit Line Clock TxSERCLK):  the exact function of this pin depends on the mode of operaton selected, as described below.  Base-Rate Mode (1.544MHz/2.048MHz) - TxSERCLK: his clock signal is used by the transmit serial interface to toth the contents on the TxSER pin into the T1/E1 framer on e rising edge of TxSERCLK. This pin can be configured as put or output as described below.  In the TxSERCLK is configured as Input:  In this pin will be an input if the TxSERCLK is chosen as the ming source for the transmit framer. Users must provide a 544MHz clock rate to this input pin for T1 mode of operaton, and 2.048MHz clock rate in E1 mode.  In the TxSERCLK is configured as Output:  In this pin will be an output if either the recovered line clock or the MCLK PLL is chosen as the timing source for the T1/E1 transmit framer. The transmit framer will output a 1.544MHz clock rate in E1 mode.  Stifel High-Speed Backplane Modes* - TxSERCLK as IPUT ONLY.  It is mode, TxSERCLK is an optional clock signal input thich is used as the timing source for the transmit line interce, and is only required if TxSERCLK is chosen as the timing source for the transmit line interce, and is only required if TxSERCLK is chosen as the timing source for the transmit framer. If TxSERCLK is chosen as the timing source for the transmit line interce, and is only required if TxSERCLK is chosen as the timing source of the transmit framer. If TxSERCLK is chosen as the timing source of the transmit framer. If TxSERCLK is chosen as the timing source of the transmit source.  Standard TxSERCLK is used as the transmit line clock tall the TxMSYNC/TxINCLK high-speed clock signal.  Store I framer Bypass Mode - TxLINECLK  It his mode, TxSERCLK is used as the transmit line clock tall the TxMSYNC/TxINCLK high-speed clock signal.  Store I framer Bypass Mode - TxLINECLK  It his mode, TxSERCLK is used as the transmit line clock tall the TxMSYNC/TxINCLK high-speed clock signal.  Store I framer Bypass Mode - TxLINECLK  In DS1 high-sp

T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxSYNC/ TxNEG	59	32 data	1/O	products products not be and the products of the product of the prod	Transmit Single Frame Sync Pulse (TxSYNC) / Transmit Negative Digital Input (TxNEG): The exact function of this pin depends on the mode of operation selected, as described below.  DS1/E1 Base Rate Mode (1.544MHz/2.048MHz) - TxSYNC: These TxSYNC pin is used to indicate the single frame boundary within an outbound T1/E1 frame. In both DS1 or E1 mode, the single frame boundary repeats every 125 microseconds (8kHz).  In DS1/E1 base rate, TxSYNC can be configured as either input or output as described below.  When TxSYNC is configured as an Input: Users must provide a signal which must pulse "High" for one period of TxSERCLK during the first bit of an outbound DS1/E1 frame. It is imperative that the TxSYNC input signal be synchronized with the TxSERCLK input signal.  When TxSYNC is configured as an Output: The transmit T1/E1 framer will output a signal which pulses "High" for one period of TxSERCLK during the first bit of an outbound DS1/E1 frame.  DS1/E1 High-Speed Backplane Modes* - TxSYNC as INPUT ONLY: In this mode, TxSYNC must be an input regardless of the clook source that is chosen to be the timing source for the transmit framer. In 2.048MVIP/4.096/8.192MHz high-speed modes, the TxSYNC pin must be pulsed 'High' for one period of TxSERCLK during the first bit of the outbound T1/E1 frame. In HMVIP mode, TxSYNC0 must be pulsed 'High' for one period of TxSERCLK during the first bit of the outbound T1/E1 frame. In HMVIP mode, TxSYNC0 must be pulsed 'High' for one period of TxSERCLK during the first bit of the outbound T1/E1 frame. In HMVIP mode, TxSYNC0 must be pulsed 'High' for one period of TxSERCLK during the first bit of the outbound T1/E1 frame. In HMVIP mode, TxSYNC0 must be pulsed 'High' for one period of TxSERCLK during the first bit of the outbound T1/E1 frame. In HMVIP, H.00, Bit-multiplexed frame.  DS1 or E1 Framer Bypass Mode - TxNEGn  In this mode, TxSYNC is used as the negative digital input pin (TxNEG) to the LIU.  NOTE: 'High-speed backplane modes, and (For T1/E1) 2.048MVIP, 4.096MHz, 8.192MHz, 16.

# EXAR Powering Connectivity\*

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION							
TxMSYNC/ TxINCLK	58	31	I/O	12	Multiframe Sync Pulse (TxMSYNC) / Transmit Input Clock (TxINCLK)  The exact function of this pin depends on the mode of operation selected, as described below.  DS1/E1 Base Rate Mode (1.544MHz/2.048MHz) - TxM-SYNC  In this mode, this pin is used to indicate the multi-frame boundary within an outbound DS1/E1 frame.  In DS1 ESF mode, TxMSYNC repeats every 3ms.  In DS1 SF mode, TxMSYNC repeats every 1.5ms.  In E1 mode, TxMSYNC repeats every 2ms.  If TxMSYNC is configured as an input, TxMSYNC must pulse "High" for one period of TxSERCLK during the first bit of an outbound DS1/E1 multi-frame. It is imperative that the TxM-SYNC input signal be synchronized with the TxSERCLK input signal.  If TxMSYNC is configured as an output, the transmit section of the T1/E1 framer will output and pulse TxMSYNC "High" for one period of TxSERCLK during the first bit of an outbound DS1/E1 frame.  DS1/E1 High-Speed Backplane Modes* - (TxINCLK as							
				or produc	or produ	or produ	or produ	or produ	In this mode, TxINCLK0 must be used as the high-speed input clock pin for the backplane interface to latch in high-speed or multiplexed data on the TxSER pin. The frequency of TxINCLK0 is presented in the table below.  OPERATION MODE  FREQUENCY OF TXINCLK0 (MHz)			
				3100	2.048MVIP non-multiplexed 2.048							
			000	or property of	is not	et not	ay not	et not	et not	et not	et lot	4.096MHz non-multiplexed 4.096
		6	Sh								8.192MHz non-multiplexed 8.192	
		146	3			12.352MHz Bit-multiplexed 12.352 (DS1 ONLY)						
			9		16.384MHz Bit-multiplexed 16.384							
					16.384 HMVIP Byte-multiplexed 16.384							
					16.384 H.100 Byte-multiplexed 16.384							
					Notes:  1. *High-speed backplane modes include (For T1/E1) 2.048MVIP, 4.096MHz, 8.192MHz, 16.384MHz HMVIP, H.100, Bit-multiplexed modes, and (For T1 only) 12.352MHz Bit-multiplexed mode.  2. In DS1 high-speed modes, the DS-0 data is mapped into an E1 frame by ignoring every fourth time slot (don't care).  3. This pin is internally pulled "Low".							

T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxCHCLK	49	n/a	0	8 and the second	Transmit Channel Clock Output Signal (TxCHCLK):  The exact function of this pin depends on whether or not the transmit framer enables the transmit fractional/signaling interface to input fractional data, as described below.  If transmit fractional/signaling interface is disabled:  This pin indicates the boundary of each time slot of an outbound DS1/E1 frame. In T1 mode, this output pin is a 192kHz clock which pulses "High" during the LSB of each 24 time slots. In E1 mode, this output pin is a 256kHz clock which pulses "High" during the LSB of each 32 time slots. The Terminal Equipment can use this clock signal to sample the TxCHN0 through TxCHN4 time slot identifier pins to determine which time slot is being processed.  If transmit fractional/signaling interface is enabled:  TxCHCLK is the fractional interface clock which either outputs a clock signal for the time slot that has been configured to input fractional data, or outputs an enable signal for the fractional time slot so that fractional data can be clocked into the device using the TxSERCLK pin.  Note: Transmit fractional interface can be enabled by programming to bit 4 - TxFr1544/TxFr2048 bit from register 0x0120 to '1'.  This pin is internally pulled "Low"
		ne produ	net and a	products not be or	ete <sup>C</sup>



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxCHN0/ TxSIG	53	n/a	o she and and	or production of the state of t	Transmit Time Slot Octet Identifier Output 0 (TxCHN0) / Transmit Serial Signaling Input (TxSIG):  The exact function of this pin depends on whether or not the transmit framer enables the transmit fractional/signaling interface, as described below:  If transmit fractional/signaling interface is disabled - TxCHN0:  These output pins (TxCHN4 through TxCHN0) reflect the five-bit binary value of the current time slot being processed by the transmit serial interface. Terminal Equipment can use the TxCHCLK to sample the five output pins of in order to identify the time slot being processed. This pin indicates the Least Significant Bit (LSB) of the time slot channel being processed. If transmit fractional/signaling interface is enabled - TxSIG:  This pin can be used to input robbed-bit signaling data to be inserted within an outbound DS1 frame or to input Channel Associated Signaling (CAS) data within an outbound E1 frame, as described below.  T1 Mode: Signaling data (A,B,C,D) must be provided on bit 4,5,6,7 of each time slot on the TxSIG pin if 16-code signaling is used. If 4-code signaling is selected, signaling data (A,B) must be provided on bit 4,5 of each time slot on the TxSIG pin If 2-code signaling is selected, signaling data (A) must be provided on bit 4 of each time slot on the TxSIG pin.  E1 Mode: Signaling data in E1 mode can be provided on the TxSIG pin on a time-slot-basis as in T1 mode, or it can be provided on time slot 16 only via the TxSIG input pin. In the latter case, signaling data (A,B,C,D) of channel 1 and channel 17 must be inserted on the TxSIG pin during time slot 16 of frame 1, signaling data (A,B,C,D) of channel 2 and channel 18 must be inserted on the TxSIG pin during time slot 16 of frame 2etc. The CAS multiframe Alignments bits (0000 bits) and the extra bits/alarm bit (xyxx) must be inserted on the TxSIG pin during time slot 16 of frame 0.  Note: Transmit fractional interface can be enabled by programming to bit 4 - TxFr1544/TxFr2048 bit from register 0x0120 to '1'.



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxCHN1/ TxFrTD	50	n/a	I/O	8	Transmit Time Slot Octet Identifier Output 1 (TxCHN1) / Transmit Serial Fractional Input (TxFrTD):  The exact function of this pin depends on whether or not the transmit framer enables the transmit fractional/signaling interface, as described below:  If transmit fractional/signaling interface is disabled - TxCHN1  These output signals (TxCHN4 through TxCHN0) reflect the five-bit binary value of the current time slot being processed by the transmit serial interface. Terminal Equipment can use the TxCHCLK to sample the five output pins in order to identify the time slot being processed. This pin indicates Bit 1 of the time slot channel being processed.  If transmit fractional/signaling interface is enabled - TxFrTDn  This pin is used as the fractional data input pin to input fractional DS1/E1 payload data which will be inserted within an outbound DS1/E1 frame. In this mode, terminal equipment can use either TxCHCLK or TxSERCLK to clock in fractional DS1/E1 payload data depending on the framer configuration.  Notes:  1. Transmit fractional/Signaling interface can be enabled by programming to bit 4 - TxFr1544/
TxCHN2/ Tx32MHz	47	n/a	o O The Branch of the Branch o	rodund rotbeord	TxFr2048 bit from register 0x0120 to '1'.  This pin is internally pulled "Low".  Transmit Time Slot Octet Identifier Output 2 (TxCHN2) / Transmit 32.678MHz Clock Output (Tx32MHZ):  The exact function of this pin depends on whether or not the transmit framer enables the transmit fractional/signaling interface, as described below:  If transmit fractional/signaling interface is disabled - TxCHN2  These output signals (TxCHN4 through TxCHN0) reflect the five-bit binary value of the current time slot being processed by the transmit serial interface. Terminal Equipment can use the TxCHCLK to sample the five output pins in order to identify the time slot being processed. This pin indicates Bit 2 of the time slot channel being processed.  If transmit fractional/signaling interface is enabled - Tx32MHz  This pin is used to output a 32.678MHz clock reference which is derived from the MCLKIN input pin.  Note: Transmit fractional interface can be enabled by programming to bit 4 - TxFr1544/TxFr2048 bit from register 0x0120 to '1'.



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxCHN3/ TxOHSYNC	46	n/a	0	8	Transmit Time Slot Octet Identifier Output 3 (TxCHN3) / Transmit Overhead Synchronization Pulse (TxOHSYNC):
					The exact function of this pin depends on whether or not the transmit framer enables the transmit fractional/signaling interface, as described below:
					If transmit fractional/signaling interface is disabled - TxCHN3
					These output signals (TxCHN4 through TxCHN0) reflect the five-bit binary value of the current time slot being processed by the transmit serial interface. Terminal Equipment can use the TxCHCLK to sample the five output pins in order to identify the time slot being processed. This pin indicates Bit 3 of the time slot channel being processed.
					If transmit fractional/signaling interface is enabled - TxOHSYNC
					This pin is used to output an Overhead Synchronization Pulse which indicates the first bit of each multi-frame.
					NOTE: Transmit fractional interface can be enabled by programming to bit 4 - TxFr1544/TxFr2048 bit from register 0x0120 to '1'.
TxCHN4	45	n/a	0	or produ	Transmit Time Slot Octet Identifier Output-Bit 4 (TxCHN4):  These output signals (TxCHN4 through TxCHN0) reflect the five-bit binary value of the current time slot being processed by the transmit serial interface. Terminal Equipment can use the TxCHCLK to sample the five output pins in order to identify the time slot being processed. This pin indicates the Most Significant Bit (MSB) of the time slot channel being processed.
		Theda	and	lot ho	

# TRANSMIT OVERHEAD INTERFACE

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TXOH	51	n/a	1	Products product products products products products product products products products products products products product product	Transmit Overhead Input (TxOH):  The exact function of this pin depends on the mode of operation selected, as described below.  DS1 Mode  This pin operate as the source of Datalink bits which will be inserted into the Datalink bits within an outbound DS1 frame if the framer is configured accordingly. Datalink Equipment can provide data to this input pin using the TxOHCLK clock at either 2kHz or 4kHz depending on the transmit datalink bandwidth selected.  Note: This input pin will be disabled if the framer is using the Transmit HDLC Controller, or the TxSER input as the source for the Data Link Bits.  E1 Mode  This pin operates as the source of Datalink bits or Signaling bits depending on the framer configuration, as described below.  Sourcing Datalink bits from TxOH:  The E1 transmit framer will output a clock edge on TxOHCLK for each Sa bit that has been configured to carry datalink information. Terminal equipment can then use TxOHCLK to
		e pros	No. 31	W.	and the extra bits/alarm bit (xyxx) must be inserted on the TxOH pin during time slot 16 of frame 0.  Note: This pin is internally pulled "Low".



#### TRANSMIT OVERHEAD INTERFACE

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
TxOHCLK	57	n/a	0	8	Transmit OH Serial Clock Output Signal(TxOHCLK)  This pin functions as an overhead output clock signal for the transmit overhead interface, and its function is explained below.  DS1 Mode  If the TxOH pin has been configured to be the source for Datalink bits, the DS1 transmit framer will provide a clock edge for each Data Link Bit. In DS1 ESF mode, the TxOHCLK can either be a 2kHz or 4kHz output signal depending on the selection of Data Link Bandwidth (Register 0x010A).  Data Link Equipment can provide data to the TxOH pin on the rising edge of TxOHCLK. The framer latches the data on the falling edge of this clock signal.  E1 Mode  If the TxOH pin has been configured to be the source for Data Link bits, the E1 transmit framer will provide a clock edge for each National Bit (Sa bits) that has been configured to carry data link information. (Register 0x010A)
		Thep	is and and	corproduce a service of the service	each National Bit (Sa bits) that has been configured to carry data link information. (Register 0x010A)

# RECEIVE OVERHEAD INTERFACE

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE(MA)	DESCRIPTION
RxOH	26	n/a	0	8	Receive Overhead Output (RxOH): This pin functions as the Receive Overhead output, or Receive Signaling Output depending on the receive framer configuration, as described below. DS1 Mode
					If the RxOH pin has been configured as the destination for the Data Link bits within an inbound DS1 frame, datalink bits will be output to the RxOH pin at either 2kHz or 4kHz depending on the Receive datalink bandwidth selected. (Register 0x010C).  If configured appropriately, signaling information in the receive signaling array registers (Registers 0x0500-0x051F)
				aucts)	can also be output to the RxOH output pin.  E1 Mode  This output pir will always output the contents of the National Bits (Sa4 through Sa8) if these Sa bits have been configured to carry Data Link information (Register 0x010C). The Receive Overhead Output Interface will provide a clock edge on RxOHCLK for each Sa bit carrying Data Link information. If configured appropriately, signaling information in the receive signaling array registers (Registers 0x0500-0x051F) can also be output to the RxOH output pin.
RxOHCLK	31	n/a	o of the state of	Pro 8 long	Receive Overhead Clock Output (RxOHCLK): This pin functions as an overhead output clock signal for the receive overhead interface, and its function is explained below.  DS1 Mode If the RxOH pin has been configured to be the destination for Datalink bits, the DS1 transmit framer will output a clock edge for each Data Link Bit. In DS1 ESF mode, the RxOHCLK can either be a 2kHz or 4kHz output signal depending on the selection of Data Link Bandwidth (Register 0x010C).  Data Link Equipment can clock out datalink bits on the RxOH pin using this clock signal.
		<b>M</b>			E1 Mode  The E1 receive framer provides a clock edge for each National Bit (Sa bits) that is configured to carry data link information.  Data Link Equipment can clock out datalink bits on the RxOH pin using this clock signal.



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RxSYNC/ RxNEG	33	Theod	o duck and and	of production of the state of t	Receive Single Frame Sync Pulse (RxSYNC):  The exact function of this pin depends on the mode of operation selected, as described below.  DS1/E1 Base Rate Mode (1.544MHz/2.048MHz) - RxSYNC:  This RxSYNC pin is used to indicate the single frame boundary within an inbound T1/E1 frame. In both DS1 or E1 mode, the single frame boundary repeats every 125 microseconds (8kHz).  In DS1/E1 base rate, RxSYNC can be configured as either input or output depending on the slip buffer configuration as described below.  When RxSYNC is configured as an Input:  Users must provide a signal which must pulse "High" for one period of RxSERCLK and repeats every 125µS. The receive serial Interface will output the first bit of an inbound DS1/E1 frame during the provided RxSYNC pulse.  Note: It is imperative that the RxSYNC input signal be synchronized with the RxSERCLK input signal.  When RxSYNC is configured as an Output:  The receive F1/E1 framer will output a signal which pulses High" for one period of RxSERCLK during the first bit of an inbound DS3/E1 frame.  DS1/E1 High-Speed Backplane Modes* - RxSYNC as INPUT ONLY:  In this mode, RxSYNC must be an input regardless of the slip buffer configuration. In 2.048MVIP/4.096/8.192MHz high-speed modes, the RxSYNC pin must be pulsed 'High' for one period of RxSERCLK during the first bit of the inbound T1/E1 frame. In HMVIP mode, RxSYNC0 must be pulsed 'High' for 4 clock cycles of the RxSERCLK signal in the position of the first two and the last two bits of a multiplexed frame. In H.100 mode, RxSYNC0 must be pulsed 'High' for 4 clock cycles of the RxSERCLK signal in the position of the first and the last bit of a multiplexed frame.  DS1 or E1 Framer Bypass Mode - RxNEGn  In this mode, RxSYNC is used as the Receive negative digital output pin (RxNEG) from the LIU.  Note: *High-speed backplane modes include (For T1/E1) 2.048MVIP, 4.096MHz, 8.192MHz, 16.384MHz HMVIP, H.100, Bit-multiplexed modes, and (For T1 only) 12.352MHz Bit-multiplexed modes, and (For T1 only) 12.352MHz Bit-multiplexed mode



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RXCRCSYNC	39	22	0	12	Receive Multiframe Sync Pulse (RxCRCSYNC): The RxCRCSYNC pin is used to indicate the receive multiframe boundary. This pin pulse "High" for one period of RxSERCLK when the first bit of an inbound DS1/E1 Multiframe is being output on the RxCRCSYNC pin.  In DS1 ESF mode, RxCRCSYNC repeats every 3ms In DS1 SF mode, RxCRCSYNC repeats every 1.5ms In E1 mode, RxCRCSYNC repeats every 2ms.
RXCASYNC	30	19	0	12	Receive CAS Multiframe Sync Pulse (RxCASYNC):  - E1 Mode Only  The RxCASYNC pin is used to indicate the E1 CAS Multif- frame boundary. This pin pulses "High" for one period of RxSERCLK when the first bit of an E1 CAS Multi-frame is being output on the RxCASYNC pin.
		le prodiction of the production of the productio	ne de la constante de la const	products not be ord	RXSERCLK when the first bit of an E1 CAS Multi-frame is being output on the RxCASYNC pin.

# EXAR Powering Connectivity\*

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTI	ON
RxSERCLK/ RxLINECLK	42	24	1/0	12	Receive Serial Clock Signal (Rxs Clock (RxLINECLK): The exact function of this pin depetion selected, as described below. In Base-Rate Mode (1.544MHz/2. This pin is used as the receive serial interface which can be configured. The receive serial interface outputs rising edge of RxSERCLK. When RxSERCLK is configured. This pin will be an input if the slip bis enabled. System side equipment clock rate to this input pin for T1 m 2.048MHz clock rate in E4 mode. When RxSERCLK is configured. This pin will be an output if slip but receive framer will output a 1.544M of operation, and a 2.048MHz clock.	nds on the mode of opera-  048MHz) - RxSERCLK: al clock on the system side as either input or output. s data on RxSER on the  as Input: buffer on the Receive path a must provide a 1.544MHz ode of operation, and  as Output: fer is bypassed. The  1Hz clock rate in T1 mode
				or produced and the state of th	DS1/E1 High-Speed Backplane MINPUT ONLY) In this mode, this pin must be used clock for the backplane interface to tiplexed data on the RxSER pin. TI CLK is presented in the table below  OPERATION MODE  2.048MVIP non-multiplexed	I as the high-speed input o output high-speed or mul ne frequency of RxSER-
			duc	et are be	4.096MHz non-multiplexed 8.192MHz non-multiplexed	4.096 8.192
		we of	SKY	, kg	12.352MHz Bit-multiplexed (DS1 ONLY)	12.352
		1,90	6	•	16.384MHz Bit-multiplexed	16.384
			3/1		16.384 HMVIP Byte-multiplexed	16.384
					16.384 H.100 Byte-multiplexed	16.384
					2.048MVIP, 4.096MHz, HMVIP, H.100, Bit-multip only) 12.352MHz Bit-mult 2. For DS1 high-speed m	lexed modes, and (For T iplexed mode.





SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RxSERCLK/ RxLINECLK	42	24	I/O	12	(Continued) DS1 or E1 Framer Bypass Mode - RxLINECLK In this mode, RxSERCLK is used as the Receive Line Clock output pin (RxLineClk) from the LIU.  Note: This pin is internally pulled "High".
RxSER/ RxPOS	44	26		products products products	Receive Serial Data Output (RxSER):  The exact function of this pin depends on the mode of operation selected, as described below.  DS1/E1 Mode - RxSER  This pin functions as the receive serial data output on the system side interface, which updates on the rising edge of the RxSERCLK pin. All the framing alignment bits, facility data link bits, CRC bits, and signaling information will also be extracted to this output pin.  DS1 or E1 High-Speed Multiplexed Mode* - RxSER  In this mode, this pin is used as the high-speed multiplexed data output pin on the system side. High-speed multiplexed data will output on RxSER in a byte or bit-interleaved way. The framer outputs the multiplexed data on RxSER using the high-speed input clock (RxSERCLK).  DS1 or E1 Framer Bypass Mode  In this mode, RxSER is used as the positive digital output pin (RxPOS) from the LIU.  Note: *High-speed multiplexed modes include (For T1/E1) 16.384MHz HMVIP, H.100, Bit-multiplexed modes, and (For T1 only) 12.352MHz Bit-multiplexed mode.  Note: In DS1 high-speed modes, the DS-0 data is mapped into an E1 frame by ignoring every fourth time slot (don't care).
	N'	le production	may		

# EXAR Powering Connectivity

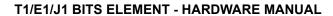
SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RxCHN0/ RxSig	40	n/a	0	8	Receive Time Slot Octet Identifier Output (RxCHN0) / Receive Serial Signaling Output (RxSIG):
					The exact function of this pin depends on whether or not the receive framer enables the receive fractional/signaling interface, as described below:
					If receive fractional/signaling interface is disabled - RxCHN0:
					These output pins (RxCHN4 through RxCHN0) reflect the five-bit binary value of the current time slot being output by the receive serial interface. System equipment can use the RxCHCLK to sample the five output pins to identify the time slot being output on this pin. RxCHN0 indicates the Least Significant Bit (LSB) of the time slot channel being output.
					If receive fractional/signaling interface is enabled - RxSIG:  This pin can be used to output robbed-bit signaling data within an inbound DS1 frame or to output Channel Associated Signaling (CAS) data within an inbound E1 frame, as described below.
				HUS	<b>T1 Mode:</b> Signaling data (A,B,C,D) will be output on bit 4,5,6,7 of each time slot on the RxSIG pin if 16-code signaling is used. If 4-code signaling is selected, signaling data (A,B) will be output on bit 4, 5 of each time slot on the RxSIG pin. If 2-code signaling is selected, signaling data (A) will be output on bit 4 of each time slot on the RxSIG pin.
			auc'i	or produced a service of the service	E1 Mode: Signaling data in E1 mode will be output on the RxSIG pin on a time-slot-basis as in T1 mode, or it can be output on time slot 16 only via the RxSIG output pin. In the latter case, signaling data (A,B,C,D) of channel 1 and channel 17 will be output on the RxSIG pin during time slot 16 of frame 1, signaling data (A,B,C,D) of channel 2 and channel 18 will be output on the RxSIG pin during time slot 16 of
		e Pr	She	ay no	frame 2etc. The CAS multiframe Alignments bits (0000 bits) and the extra bits/alarm bit (xyxx) will be output on the RxSIG pin during time slot 16 of frame 0.
		11199	and		<b>NOTE:</b> Receive Fractional/signaling interface can be enabled by programming to bit 4 - RxFr1544/RxFr2048 bit from register 0x0122 to '1'.



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RxCHN1/ RxFrTD	36	n/a	0	8	Receive Time Slot Octet Identifier Output Bit 1 (RxCHN1) / Receive Serial Fractional Output (RxFrTD):
					The exact function of this pin depends on whether or not the receive framer enables the receive fractional/signaling interface, as described below:
					If receive fractional/signaling interface is disabled - RxCHN1:
					These output pins (RxCHN4 through RxCHN0) reflect the five-bit binary value of the current time slot being output by the receive serial interface. System equipment can use the RxCHCLK to sample the five output pins to identify the time slot being output on this pin. RxCHN1 indicates Bit 1 of the time slot channel being output.
					If receive fractional/signaling interface is enabled - RxFrTD:
					This pin is used as the fractional data output pin to output fractional DS1/E1 payload data within an inbound DS1/E1 frame. In this mode, system equipment can use either RxCH-CLK or RxSERCLK to clock out fractional DS1/E1 payload data depending on the framer configuration.
				cts	NOTE: Receive Fractional/Signaling interface can be enabled by programming to bit 4 - RxFr1544/RxFr2048 bit
RxCHN2/ RxCHN	32	n/a	0	productions	Receive Time Slot Octet Identifier Output-Bit 2 (RxCHN2) / Receive Time Slot Identifier Serial Output (RxCHN): The exact function of this pin depends on whether or not the receive framer enables the receive fractional/signaling interface, as described below:
			CV 2	10,00	If receive fractional/signaling interface is disabled - RxCHN2:
	~	le data	may	production of the hot be ordered to the hot	These output pins (RxCHN4 through RxCHN0) reflect the five-bit binary value of the current time slot being output by the receive serial interface. System equipment can use the RxCHCLK to sample the five output pin to identify the time slot being output on this pin. RxCHN2 indicates Bit 2 of the time slot channel being output.  If receive fractional/signaling interface is enabled - RxCHNn  This pin serially outputs the five-bit binary value of the time
					slot being output by the receive serial interface.
					<b>NOTE:</b> Receive Fractional/Signaling interface can be enabled by programming to bit 4 - RxFr1544/RxFr2048 bit from register 0x0122 to '1'.



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RxCHN3/ Rx8KHZ	28	n/a	0	8	Receive Time Slot Octet Identifier Output-Bit 3 (RxCHN3) / Receive 8KHz Clock Output (Rx8KHZ):  The exact function of this pin depends on whether or not the receive framer enables the receive fractional/signaling interface, as described below:  If receive fractional/signaling interface is disabled - RxCHN3:  These output pins (RxCHN4 through RxCHN0) reflect the five-bit binary value of the current time slot being output by the receive serial interface. System equipment can use the RxCHCLK to sample the five output pin to identify the time slot being output on this pin. RxCHN3 indicates Bit 3 of the time slot channel being output.  If receive fractional/signaling interface is enabled - Rx8KHZ:  This pin outputs a reference 8KHz clock signal derived from the MCLKIN input.  Note: Receive Fractional/Signaling interface can be enabled by programming to bit 4 - RxFr1544/RxFr2048 bit from register 0x0122 to '1'.
RxCHN4/ RxSCLK	27	18	o duck	or produced and the second sec	Receive Time Slot Octet Identifier Output-Bit 4 (RxCHN4) / Receive Recovered Line Clock Output (RxSCLK): The exact function of this pin depends on whether or not the receive framer enables the receive fractional/signaling interface, as described below:  If receive fractional/signaling interface is disabled - RxCHN4: These output pins (RxCHN4 through RxCHN0) reflect the five-bit binary value of the current time slot being output by the receive serial interface. System equipment can use the RxCHCLK to sample the five output pin to identify the time slot being output on this pin. RxCHN4 indicates the Most Significant Bit (MSB) of the time slot channel being output.  If receive fractional/signaling interface is enabled - Receive Recovered Line Clock Output (RxSCLK): This pin outputs the recovered T1/E1 line clock (1.544MHz in T1 mode and 2.048MHz in E1 mode).  Note: Receive Fractional/Signaling interface can be enabled by programming to bit 4 - RxFr1544/RxFr2048 bit from register 0x0122 to '1'.



SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RXCHCLK	38	n/a	0	8	Receive Channel Clock Output (RxCHCLK):  The exact function of this pin depends on whether or not the receive framer enables the receive fractional/signaling interface to output fractional data, as described below.  If receive fractional/signaling interface is disabled:  This pin indicates the boundary of each time slot of an inbound DS1/E1 frame. In T1 mode, this output pin is a 192kHz clock which pulses "High" during the LSB of each 24 time slots. In E1 mode, this output pin is a 256kHz clock which pulses "High" during the LSB of each 32 time slots. System Equipment can use this clock signal to sample the RxCHN0 through RxCHN4 time slot identifier pins to determine which time slot is being output.  If receive fractional/signaling interface is enabled:  RxCHCLK is the fractional interface clock which either outputs a clock signal for the time slot that has been configured to output fractional data, or outputs an enable signal for the fractional time slot so that fractional data can be clocked out of the device using the RxSERCLK pin.  Note: Receive fractional interface can be enabled by programming to bit 4 - RxFr1544/RxFr2048 bit from register 0x0122 to '1'.
	~	ne production of the productio	neet a	products, not be ord	ered

# RECEIVE LINE INTERFACE

SIGNAL NAME	128-Pin#	80-Pin#	Түре	OUTPUT DRIVE (MA)	DESCRIPTION
RTIP	14	9	I	-	Receive Positive Analog Input (RTIP):  RTIP is the positive differential input from the line interface. This input pin, along with the RRING input pin, functions as the "Receive DS1/E1 Line Signal" input for the XRT86VL30 device.  The user is expected to connect this signal and the RRING input signal to a 1:1 transformer for proper operation. The center tap of the receive transformer should have a bypass capacitor of 0.1μF to ground (Chip Side) to improve long haul application receive capabilities.
RRING	13	8	ı	-	Receive Negative Analog Input (RRING): RRING is the negative differential input from the line interface. This input pin, along with the RTIP input pin, functions as the "Receive DS1/E1 Line Signal" input for the XRT86VL30 device.  The user is expected to connect this signal and the RTIP input signal to a 1:1 transformer for proper operation. The center tap of the receive transformer should have a bypass capacitor of 0.1 µF to ground (Chip Side) to improve long haul application receive capabilities.
RxLOS	43	The plant of the p	o duction and and	or produce a series of the ser	Receive Loss of Signal Output Indicator (RLOS):  The XRT86VL30 device will assert this output pin (i.e., toggle it "high") anytime (and for the duration that) the Receive DS1/E1 Framer or LIU block declares the LOS defect condition.  Conversely, the XRT86VL30 device will tri-state this output pin anytime (and for the duration that) the Receive DS1/E1 Framer or LIU block is NOT declaring the LOS defect condition.  Notes:  1. This output pin will toggle "high" (to denote that LOS is being declared) whenever either the Receive DS1/E1 Framer or the Receive DS1/E1 LIU block declares the LOS defect condition. In other words, the state of this output pin is a logic OR of the Framer LOS and the LIU LOS condition.  2. Since the XRT86VL30 device tri-states this output pin (anytime the channel is NOT declaring the LOS defect condition). Therefore, the user MUST connect a "pull-down" resistor (ranging from 1K to 10K) to the RxLOS output pin, in order to pull this output pin to the logic "LOW" condition, whenever the Channel is NOT declaring the LOS defect condition.



# TRANSMIT LINE INTERFACE

SIGNAL NAME	128-PIN#	80-Pin#	Түре	DESCRIPTION
TTIP	8	5	0	Transmit Positive Analog Output (TTIP):  TTIP is the positive differential output to the line interface. This output pin, along with the corresponding TRING output pin, function as the Transmit DS1/E1 output signal drivers for the XRT86VL30 device.  The user is expected to connect this signal and the corresponding TRING output signal to a 1:2 step up transformer for proper operation.  This output pin will be tri-stated whenever the user sets the "TxON" input pin or register bit (0x0F02, bit 3) to "0".  Note: This pin should have a series line capacitor of 0.68μF for DC blocking purposes.
TRING	6	3	0	Transmit Negative Analog Output (TRING):  TRING is the negative differential output to the line interface. This output pin, along with the corresponding TTIP output pin, function as the Transmit DS1/E1 output signal drivers for the XRT86VL30 device.  The user is expected to connect this signal and the corresponding TRING output signal to a 1:2 step up transformer for proper operation.  Note: This output pin will be tri-stated whenever the user sets the "TxON" input pin or register bit (0x0F02, bit 3) to "0".
TxON	128	79		Transmitter On  This input pin permits the user to either enable or disable the Transmit Output Driver within the Transmit DS1/E1 LIU Block. If the TxON pin is pulled "Low", the output driver is tri-stated. When this pin is pulled 'High', turning on or off the transmitter will be determined by the appropriate channel register (address 0x0F02, bit 3)  DOW = Disables the Transmit Output Driver within the Transmit DS1/E1 LIU Block in this setting, the TTIP and TRING output pins will be tri-stated.  HIGH = Enables the Transmit Output Driver within the Transmit DS1/E1 LIU Block. In this setting, the corresponding TTIP and TRING output pins will be enabled or disabled by programming the appropriate channel register (address 0x0F02, bit 3)  NOTE: Whenever the transmitters are turned off, the TTIP and TRING output pins will be tri-stated.

TIMING INTE	RFACE	data	, III	
SIGNAL NAME	128-PIN#	80-Pin#	TYPE	DESCRIPTION
MCLKIN	24	17	I	Master Clock Input: This pin is used to provide the timing reference for the internal master clock of the device. The frequency of this clock is programmable from 1.544Mhz to 16.384MHz in register 0x0FE9.  Note: For HMVIP mode, this pin should be set to 1.544MHz or 2.048MHz.
MCLKnOUT	25	n/a	0	LIU T1/E1 Output Clock Reference  This output clock depends on the mode of operation. In T1 mode, this output pin is defaulted to 1.544MHz, but can be programmed to output 3.088MHz, 6.176MHz, or 12.352MHz in register 0x0FE4. In E1 mode, this output pin is defaulted to 2.048MHz, but can be programmed to 4.096MHz, 8.192MHz, or 16.384MHz in register 0x0FE4.



# TIMING INTERFACE

SIGNAL NAME	128-Pin#	80-Pin#	Түре	DESCRIPTION		
OSCCLK	86	n/a	I/O	Framer T1/E1 Output Clock Reference This output clock depends on the mode of operation. In T1 mode, this output pin is defaulted to 1.544MHz, but can be programmed to output 49.408MHz in register 0x011E. In E1 mode, this output pin is defaulted to 2.048MHz, but can be programmed to 65.536MHz in register 0x011E.  Note: This pin is internally pulled "Low"		
8KSYNC	88	n/a	I/O	8kHz Clock Output Reference This pin is an output reference of 8kHz based on the MCLKIN input. Therefore, the duty cycle of this output is determined by the time period of the input clock reference.  Note: This pin is internally pulled "Low"		
8KEXTOSC	122	n/a	I	External Oscillator Select For normal operation, this pin should not be used, or pulled "Low".  Note: This pin is internally pulled "Low"		
ANALOG	19	n/a	0	Factory Test Mode Pin  Note: For Internal Use Only		
LOP	1	n/a	I	Loss of Power for E1 Only This is a Loss of Power pin in the E1 application only. Upon detecting LOP in E1 mode, the device will automatically transmit the Sa5 and Sa6 bit to a different pattern, so that the Receive terminal can detect a power failure in the network  Please see register 0x0131 for the Transmit SA control.		
GPIO CONTROL GI PIO GOLDEN						

#### **GPIO CONTROL**

SIGNAL NAME	128-Pin#	80-Pin#	Түрв	7	10	DESCRIPTION
GPIO_3	119	75	WO	Ge	nera	l Purpose Input/Output Pins
GPIO_2	118	74	0	Th	e GP	IO pins can be used as either inputs or outputs selected by register
GPIO_1	116	72	100			By default, these pins are inputs. To configure a GPIO pin to be an
GPIO_0	117	73	S, 4	o O	iput,	the register bit must be set to "1".

#### **JTAG**

SIGNAL NAME	128-Pin#	80-Pin#	Түре	DESCRIPTION
TCK	111	n/a	I	Test clock: Boundary Scan Test clock input:  The TCLK signal is the clock for the TAP controller, and it generates the boundary scan data register clocking. The data on TMS and TDI is loaded on the positive edge of TCK. Data is observed at TDO on the falling edge of TCK.
TMS	114	n/a	ı	Test Mode Select: Boundary Scan Test Mode Select input. The TMS signal controls the transitions of the TAP controller in conjunction with the rising edge of the test clock (TCK).  Note: 1. For normal operation this pin MUST be pulled "High".  2. This pin is internally pulled 'high'

T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

# JTAG

SIGNAL NAME	128-Pin#	80-Pin#	Түре	DESCRIPTION
TDI	113	n/a	I	Test Data In: Boundary Scan Test data input The TDI signal is the serial test data input.  Note: This pin is internally pulled 'high'.
TDO	115	n/a	0	Test Data Out: Boundary Scan Test data output The TDO signal is the serial test data output.
TRST	112	n/a	I	Test Reset Input: The TRST signal (Active Low) asynchronously resets the TAP controller to the Test-Logic-Reset state.  Note: 1. This pin is internally pulled 'high'
TEST	121	n/a	I	Factory Test Mode Pin  Note: This pin is internally pulled low', and should be pulled 'low' for normal operation.
aTEST	120	n/a	I	Factory Test Mode Pin  Note: This pin is internally pulled 'low', and should be pulled 'low' for normal operation.
SENSE	18	n/a	I	Factory Test Mode Pin Note: User should tie this pin to ground
JTAG_Ring	10	n/a	I	ATP_Ring Test Pin  This analog test pin is used for testing the continuity between the TTIP/ TRING, RTIP/RRING and the on-board transformer.
JTAG_Tip	11	n/a	্ব	ATP_Tip Test Pin This analog test pin is used for testing the continuity between the TTIP/ TRING, RTIP/RRING and the on-board transformer.

MICROPROCI		Nogr	e de la constant de l	not be
SIGNAL NAME	128-Pin#	80-Pin#	TYPE	DESCRIPTION
DATA0	69	40	1/0	Bidirectional Microprocessor Data Bus
DATA1	70	<b>6</b> 41		These pins are used to drive and receive data over the bi-directional data
DATA2	90	547		bus, whenever the Microprocessor performs READ or WRITE operations
DATA3	91	55		with the Microprocessor Interface of the XRT86VL30 device.
DATA4	101	61		When DMA interface is enabled, these 8-bit bidirectional data bus is also
DATA5	103	63		used by the T1/E1 Framer or the external DMA Controller for storing and retrieving information.
DATA6	104	64		Tetrieving information.
DATA7	106	66		

# EXAR Powering Connectivity\*

SIGNAL NAME	128-Pin#	80-Pin#	Түре	DESCRIPTION
REQU	64	37	0	DMA Cycle Request Output—DMA Controller 0 (Write):  This output pin is used to indicate that DMA transfers (Write) are requested by the T1/E1 Framer.  On the transmit side (i.e., To transmit data from external DMA controller to HDLC buffers within the XRT86VL30), DMA transfers are only requested when the transmit buffer status bits indicate that there is space for a complete message or cell.  The DMA Write cycle starts by T1/E1 Framer asserting the DMA Request (REQ0) 'low', then the external DMA controller should drive the DMA Acknowledge (ACK0) 'low' to indicate that it is ready to start the transfer. The external DMA controller should place new data on the Microprocessor data bus each time the Write Signal is Strobed low if the WR is configured as a Write Strobe. If WR is configured as a direction signal, then the external DMA controller would place new data on the Microprocessor data bus each time the Read Signal (RD) is Strobed low.  The Framer asserts this output pin (toggles it "Low") when at least one of the Transmit HDLC buffers are empty and can receive one more HDLC message.  The Framer negates this output pin (toggles it "High") when the HDLC buffer can no longer receive another HDLC message.
REQ1	61	34 Ne of	oduct	DMA Cycle Request Output—DMA Controller 1 (Read): This output pin is used to indicate that DMA transfers (Read) are requested by the T1/E1 Framer. On the receive side (i.e., To transmit data from HDLC buffers within the XRT86VL30 to external DMA Controller), DMA transfers are only requested when the receive buffer contains a complete message or cell. The DMA Read cycle starts by T1/E1 Framer asserting the DMA Request (REQ1) 'low', then the external DMA controller should drive the DMA Acknowledge (ACK1) 'low' to indicate that it is ready to receive the data. The T1/E1 Framer should place new data on the Microprocessor data bus each time the Read Signal is Strobed low if the RD is configured as a Read Strobe. If RD is configured as a direction signal, then the T1/E1 Framer would place new data on the Microprocessor data bus each time the Write Signal (WR) is Strobed low. The Framer asserts this output pin (toggles it "Low") when one of the Receive HDLC buffer contains a complete HDLC message that needs to be read by the $\mu$ C/ $\mu$ P. The Framer negates this output pin (toggles it "High") when the Receive HDLC buffers are depleted.
ĪNT	96	59	0	Interrupt Request Output: This active-low output signal will be asserted when the XRT86VL30 device is requesting interrupt service from the Microprocessor. This output pin should typically be connected to the "Interrupt Request" input of the Microprocessor. The Framer will assert this active "Low" output (toggles it "Low"), to the local $\mu$ P, anytime it requires interrupt service.

# T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

SIGNAL NAME	128-PIN#	80-Pin#	Түре				DESCRIPTION	
PCLK	68	39	I	configured to operat Mode). If the Microp	al is e in roce	only the	ut:  or used if the Microprocessor In Synchronous Modes (e.g., Por Interface is configured to op book signal to do the following.	ower PC 403 perate in this
				<ol> <li>To sample the input pins, and</li> </ol>		S*, V	VR*/R/W*, A[11:0], D[7:0], R[	D*/DS* and DBEN
				2. To update the	stat	e of	the D[7:0] and the RDY/DTA	CK output signals.
				NOTES:			<b>A</b>	
				Interface t	o o synd	pera chro	if the user has configured the in either the Intel-Asyr nous Modes. In this case, the	nchronous or the
							oled, the PCLK input pin is also out receive or output data r	
iADDR	124	n/a	I			4	" for Normal Operation.	
				NOTE: This pin is in	<u>-0</u>			
fADDR	123	n/a	I	NOTE: This pin is in	tem	ally <sub>j</sub>	h" for Normal Operation.  oulled "High"	
PTYPE0	127	78	ı	Microprocessor Ty	pe i	npu	t:	
PTYPE1	126	77		These input pins per	rmit	the	user to specify which type of	
PTYPE2	125	76	lo,	Microcontroller to be table presents the th XRT86VL30 support	inte iree ts.	erfac diffe	ed to the XRT86VL30 device rent microprocessor types th	
		odi		Microprocessor Ty These input pins per Microcontroller to be table presents the tr XRT86VL30 support  O  0  1  Note: These pins a	°PType1	°PType0	MICROPROCESSOR TYPE	
		01 2	12.7	0	0	0	Intel Asynchronous	
	.v	e in	40,	0	0	1	Motorola Asynchronous	
		10, 5		1	0	1	IBM POWER PC 403	
		o sili		Note: These pins a	re ir	nterr	nally pulled "Low"	

# EXAR Powering Connectivity\*

SIGNAL NAME	128-PIN#	80-PIN#	Түре	DESCRIPTION
RDY	74	43 43	O She and h	Ready/Data Transfer Acknowledge Output:  The exact behavior of this pin depends upon the type of Microprocessor/ Microcontroller the XRT86VL30 has been configured to operate in, as defined by the PTYPE[2:0] pins.  Intel Asynchronous Mode - RDY* - Ready Output  Tis output pin will function as the "active-low" READY output.  During a READ or WRITE cycle, the Microprocessor Interface block will toggle this output pin to the logic low level, ONLY when the Microprocessor Interface is ready to complete or terminate the current READ or WRITE cycle. Once the Microprocessor has determined that this input pin has tog- gled to the logic "low" level, then it is riow safe for it to move on and execute the next READ or WRITE cycle.  If (during a READ or WRITE cycle), the Microprocessor Interface block is holding this output pin at a logic "high" level, then the Microprocessor is expected to extend this READ or WRITE cycle, until it detects this output pin being toggled to the logic low level.  Motorola Asynchronous Mode - DTACK* - Data Transfer Acknowledge Output  Tis output pin will function as the "active-low" DTACK output.  During a READ or WRITE cycle, the Microprocessor Interface block will toggle this output pin to the logic low level, ONLY when the Microprocessor Interface is ready to complete or terminate the current READ or WRITE cycle. Once the Microprocessor has determined that this input pin has tog- gled to the logic "low" level, then it is now safe for it to move on and execute the next READ or WRITE cycle) the Microprocessor Interface block is holding this output pin at a logic "high" level, then the Microprocessor is expected to extend this READ or WRITE cycle, until it detects this output plu being toggled to the logic low level.  Power PC 403 Mode - RDY Ready Output:  This output pin will function as the "active-high" READY output.  During a READ or WRITE cycle, the Microprocessor Interface block will toggle this output pin to the logic high level, ONLY when the Microproces- or interface is ready to complet
				holding this output pin at a logic "low" level, then the Microprocessor is expected to extend this READ or WRITE cycle, until it samples this output pin being at the logic low level.  Note: The Microprocessor Interface will update the state of this output pin upon the rising edge of PCLK.



# T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

SIGNAL NAME	128-Pin#	80-Pin#	Түре	DESCRIPTION
ADDR0 ADDR1 ADDR2 ADDR3 ADDR4 ADDR5 ADDR6 ADDR7 ADDR8 ADDR8 ADDR9 ADDR10 ADDR11	75 76 77 79 80 81 82 84 89 94	44 45 46 47 48 49 50 51 53 57 58 60	I	Microprocessor Interface Address Bus Input These pins permit the Microprocessor to identify on-chip registers and Buffer/Memory locations within the XRT86VL30 device whenever it performs READ and WRITE operations with the XRT86VL30 device.  Note: These pins are internally pulled "Low", except ADDR [8:11].
DBEN	73	n/a	I	<ul> <li>Data Bus Enable Input pin.</li> <li>This active-low input pin permits the user to either enable or tri-state the Bi-Directional Data Bus pins (D[7:0]), as described below.</li> <li>Setting this input pin "low" enables the Bi-directional Data bus.</li> <li>Setting this input pin "high" tri-states the Bi-directional Data Bus.</li> <li>Note: This pin is internally pulled "Low"</li> </ul>
ALE	93	e produ	- CONTRACTOR OF THE PARTY OF TH	Address Latch Enable Input Address Strobe  The exact behavior of this pin depends upon the type of Microprocessor/ Microcontroller the XRT86VL30 has been configured to operate in, as defined by the PTYPE[2:0] pins.  Intel-Asynchronous Mode - ALE  This active-high input pin is used to latch the address (present at the Micro- processor Interface Address Bus pins (A[11:0]) into the XRT86VL30 Micro- processor Interface block and to indicate the start of a READ or WRITE cycle:  Pulling this input pin "high" enables the input bus drivers for the Address Bus input pins (A[11:0]). The contents of the Address Bus will be latched into the XRT86VL30 Microprocessor Interface circuitry, upon the falling edge of this input signal.  Motorola-Asynchronous (68K) Mode - AS*  This active-low input pin is used to latch the data residing on the Address Bus, A[11:0] into the Microprocessor Interface circuitry of the XRT86VL30 device.  Pulling this input pin "low" enables the input bus drivers for the Address Bus input pins. The contents of the Address Bus will be latched into the Micro- processor Interface circuitry, upon the falling edge of this signal.  Power PC 403 Mode - No Function -Tie to GND:  This input pin has no role nor function and should be tied to GND.
<u>CS</u>	108	68	I	Microprocessor Interface—Chip Select Input: The user must assert this active low signal in order to select the Microprocessor Interface for READ and WRITE operations between the Microprocessor and the XRT86VL30 on-chip registers and buffer/memory locations.

# EXAR Powering Connectivity\*

SIGNAL NAME	128-Pin#	80-Pin#	Түре	DESCRIPTION
RD	71	42	ı	Microprocessor Interface—Read Strobe Input:  The exact behavior of this pin depends upon the type of Microprocessor/ Microcontroller the Framer has been configured to operate in, as defined by the PTYPE[2:0] pins.  Intel-Asynchronous Mode - RD* - READ Strobe Input:  This input pin will function as the RD* (Active Low Read Strobe) input signal from the Microprocessor. Once this active-low signal is asserted, then the XRT86VL30 device will place the contents of the addressed register (or buffer location) on the Microprocessor Interface Bi-directional data bus (D[7:0]).  When this signal is negated, then the Data Bus will be tri-stated.  Motorola-Asynchronous (68K) Mode - DS* - Data Strobe:  This input pin will function as the DS* (Data Strobe) input signal.  Power PC 403 Mode - WE* - Write Enable Input:  This input pin will function as the WE* (Write Enable) input pin.  Anytime the Microprocessor Interface samples this active-low input signal (along with CS* and WR/R/W*) also being asserted (at a logic low level) upon the rising edge of PCLK, then the Microprocessor Interface will (upon the very same rising edge of PCLK) latch the contents on the Bi-Directional Data Bus (D[7:0]) into the "target" on-chip register or buffer location within the XRT86VL30 device.
		Theoli	andrandra	the very same rising edge of PCLK) latch the contents on the Bi-Directional Data Bus (D[7:0]) into the "target" on-chip register or buffer location within the XRT86VL30 device.

#### MICROPROCESSOR INTERFACE

SIGNAL NAME	128-Pin#	80-PIN#	Түре	DESCRIPTION
SIGNAL NAME	<b>128-Pin#</b> 107	80-PIN# 67	TYPE	Microprocessor Interface—Write Strobe Input The exact behavior of this pin depends upon the type of Microprocessor/ Microcontroller the XRT86VL30 has been configured to operate in, as defined by the PTYPE[2:0] pins.  Intel-Asynchronous Mode - WR* - Write Strobe Input: This input pin functions as the WR* (Active Low WRITE Strobe) input signal from the Microprocessor. Once this active-low signal is asserted, then the input buffers (associated with the Bi-Directional Data Bus pin, D[7:0]) will be enabled. The Microprocessor Interface will latch the contents on the Bi-Directional Data Bus (into the "target" register or address location, within the XRT86VL30) upon the rising edge of this input pin.  Motorola-Asynchronous Mode - R/W* - Read/Write Operation Identifi- cation Input Pin: This pin is functionally equivalent to the "R/W*" input pin. In the Motorola Mode, a "READ" operation occurs if this pin is held at a logic "1", coincident to a falling edge of the RD/DS* (Data Strobe) input pin. Similarly a WRITE operation occurs if this pin is at a logic "0", coincident to a falling edge of the RD/DS* (Data Strobe) input pin.  Power PC 403 Mode - R/W* - Read/Write Operation Identification Input: This input pin will function as the "Read/Write Operation Identification Input: This input pin will function as the "Read/Write Operation Identification Input" pin.  Anytime the Microprocessor Interface samples this input signal at a logic low (while also sampling the CS* input pin "low") upon the rising edge of PCLK, then the Microprocessor Interface will (upon the very same rising edge of PCLK) latch the contents of the Address Bus (A[11:0]) into the Microprocessor Interface circuitry, in preparation for this forthcoming READ
		orodi	ct co	This input pin will function as the "Read/Write Operation Identification Input" pin.  Anytime the Microprocessor Interface samples this input signal at a logic low (while also sampling the CS* input pin "low") upon the rising edge of PCLK, then the Microprocessor Interface will (upon the very same rising edge of PCLK) latch the contents of the Address Bus (A[11:0]) into the Microprocessor Interface circuitry, in preparation for this forthcoming READ
	<b>*</b> **	e produced and	may	high (while also sampling the CS* input pin a logic "low") upon the rising edge of PCLK, then the Microprocessor Interface will (upon the very same rising edge of PCLK) latch the contents of the Address Bus (A[11:0]) into the Microprocessor Interface circuitry, in preparation for the forthcoming WRITE operation. At some point (later in this WRITE operation) the Microprocessor will also assert the RD*/DS*/WE* input pin, and the Microprocessor Interface will then latch the contents of the Bi-Directional Data Bus (D[7:0]) into the contents of the "target" register or buffer location (within the XRT86VL30).

# EXAR Powering Connectivity\*

#### MICROPROCESSOR INTERFACE

SIGNAL NAME	128-Pin#	80-PIN#	Түре	DESCRIPTION
ACK1	62	35	- Auci	<ul> <li>DMA Cycle Acknowledge Input—DMA Controller 0 (Write): The external DMA Controller will assert this input pin "Low" when the following two conditions are met:  1. After the DMA Controller, within the Framer has asserted (toggled "Low"), the Req_0 output signal.  2. When the external DMA Controller is ready to transfer data from external memory to the selected Transmit HDLC buffer. At this point, the DMA transfer between the external memory and the selected Transmit HDLC buffer may begin. After completion of the DMA cycle, the external DMA Controller will negate this input pin after the DMA Controller within the Framer has negated the Req_0 output pin. The external DMA Controller must do this in order to acknowledge the end of the DMA cycle. This pin is internally pulled "High"  DMA Cycle Acknowledge Input—DMA Controller 1 (Read): The external DMA Controller asserts this input pin "Low" when the following two conditions are met:  1. After the DMA Controller, within the Framer has asserted (toggled "Low"), the Req_1 output signal.  2. When the external DMA Controller is ready to transfer data from the selected Receive HDLC buffer to external memory. At this point, the DMA transfer between the selected Receive HDLC buffer and the external memory may begin. After completion of the DMA cycle, the external DMA Controller will negate this input pin after the DMA Controller within the Framer has negated the Req_1 output pin. The external DMA Controller will do this in order to acknowledge the end of the DMA cycle.  Note: This pin is internally pulled "High"</li> </ul>
BLAST	100	n/a	SHO	Last Cycle of Burst Indicator Input: The Microprocessor asserts this pin "Low" when it is performing its last read or write cycle, within a burst operation.  Note: This pin is internally pulled "High"
RESET	85	52	all	$\label{eq:hardware Reset Input}                                    $





#### 1.8V POWER SUPPLY PINS

SIGNAL NAME	128-Pin#	80-PIN#	Түре	DESCRIPTION
DVDD1v8	4, 41, 56, 63, 78, 105	1, 23, 36, 65	PWR	Framer Block Power Supply
AVDD1v8	16	11	PWR	
VDDPLL1v8	20, 21	13, 14	PWR	Analog Power Supply for PLL

#### 3.3V POWER SUPPLY PINS

SIGNAL NAME	128-Pin#	80-PIN#	Түре	DESCRIPTION
DVDD3v3	2, 37, 52, 92	80, 21, 28	PWR	Framer Block Power Supply
RVDD3v3	15	10	PWR	Receiver Analog Power Supply for LIU Section
TVDD3v3	7	4	PWR	Transmitter Analog Power Supply for LIU Section

#### **GROUND PINS**

SIGNAL NAME	128-PIN#	80-PIN#	Түре	DESCRIPTION
DGND	5, 29,	2, 27,	GND	Framer Block Ground
	48, 60,	33, 62,		.0" .(",0"
	72, 83,	69, 70,		11, 46, 16
	87, 102,	71		0 0 0
	109, 110		ol'	Original
AGND	17	12	GND	Analog Ground for LIU Section
RGND	12	7	GND	Receiver Analog Ground for LIU Section
TGND	9	6	GND	Transmitter Analog Ground for LIU Section
PLLGND	22, 23	15,16	GND	Analog Ground for PLL

NO CONNECT PINS							
SIGNAL NAME	128-PIN#	80-PIN#	TYPE	DESCRIPTION			
NC	3, 34, 35, 66, 67, 98, 99	n/a	NC	Not Connected			

## EXAR Powering Connectivity\*

### ELECTRICAL CHARACTERISTICS

#### **ABSOLUTE MAXIMUMS**

Power Supply	Power Rating 80pin LQFP Package0.976W
VDD <sub>IO</sub> 0.5V to +3.465V	(at zero air flow)
VDD <sub>CORE</sub> -0.5V to +1.890V	Power Rating 128pin LQFP Package0.760W (at zero air flow)
Storage Temperature65°C to 150°C	XRT86VL30IV80 Theta ja-041.0 C/W (0 Ifpm)
Operating Temperature Range40°C to 85°C	XRT86VL30IV80 Theta ja-100 38.5 C/W (100 lfpm)
Supply Voltage GND-0.5V to +VDD + 0.5V	XRT86VL30IV80 Theta ja-200 37.0 C/W (200 lfpm)
Input Logic Signal Voltage (Any Pin)0.5V to + 5.5V	XRT86VL30IV128 Theta ja-052.61 C/W (0 Ifpm)
Input Current (Any Pin) <u>+</u> 100mA	XRT86VL30IV128 Theta ja-100 46.6 C/W (100 lfpm)
ESD Protection (HBM)>2000V	XRT86VL30IV128 Theta ja-200 44.8 C/W (200 lfpm)

#### DC ELECTRICAL CHARACTERISTICS

Test Cond	itions: TA = 25°C, VDD <sub>IO</sub> = 3.3V <u>+</u> 5% , VDD <sub>CORE</sub> = 1	.8V <u>+</u> 5%	unless	otherwis	e specifi	ed
SYMBOL	PARAMETER	Min.	TYP.	Max.	Units	Conditions
I <sub>LL</sub>	Data Bus Tri-State Bus Leakage Current	-10		+10	μA	
V <sub>IL</sub>	Input Low voltage	9		0.8	V	
$V_{IH}$	Input High Voltage	2.0		VDD	٧	
$V_{OL}$	Output Low Voltage	0.0		0.4	٧	I <sub>OL</sub> = -1.6mA
$V_{OH}$	Output High Voltage	2.4		VDD	V	I <sub>OH</sub> = 40μA
I <sub>oc</sub>	Open Drain Output Leakage Current				μA	
I <sub>IH</sub>	Input High Voltage Current (with No Pull-Up or Pull_Down resistor)	-10		10	μΑ	V <sub>IH</sub> = VDD
I <sub>IL</sub>	Input Low Voltage Current (with No Pull-Up or Pull_Down resistor)	-10		10	μA	V <sub>IL</sub> = GND
$PU_{IL}$	Input Leakage (Input with Pull-Up resistor)	-120		10	μA	V <sub>I</sub> = VDD or GND
$PD_{IL}$	Input Leakage (Input with Pull-Down resistor)	-10		120	μA	V <sub>I</sub> = VDD or GND

#### T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

TABLE 1: XRT86VL30 POWER CONSUMPTION

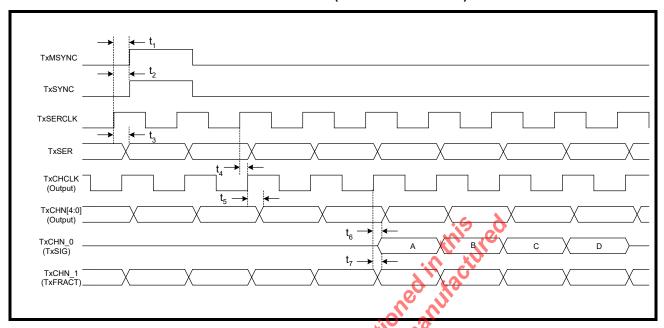
	V	OD <sub>IO</sub> = 3.3V <u>+</u>	5% , VDD <sub>CORE</sub>	= 1.8V <u>+</u> 5	% , T <sub>A</sub> =25°C,	INLESS O	THERWIS	E SPECIF	IED
Mode	SUPPLY	IMPEDANCE	TERMINATION	TRANSFO	RMER RATIO	TYP.	Max.	Unit	Test
WOOL	VOLTAGE	IMPLDANCE	RESISTOR	RECEIVER	TRANSMITTER	1115.	WAX.	ONII	Conditions
E1	3.3V	75Ω	Internal	1:1	1:2	310		mW	PRBS Pattern
	3.3V 3.465V					359	446		All ones All ones
	0.400 V						440		7 (11 01103
E1	3.3V	120Ω	Internal	1:1	1:2	300		mW	PRBS Pattern
	3.3V					336			All ones
	3.465V					.6	418		All ones
T1	3.3V	100Ω	Internal	1:1	1:2	288	(8)	mW	PRBS Pattern
	3.3V					344			All ones
	3.465V						425		All ones

#### AC ELECTRICAL CHARACTERISTICS TRANSMIT FRAMER (BASE RATE/NON-MUX)

SYMBOL	PARAMETER	TYP.	MAX.	UNITS	CONDITIONS
$t_1$	TxSERCLK to TxMSYNC delay		234	nS	
t <sub>2</sub>	TxSERCLK to TxSYNC delay		230	nS	
t <sub>3</sub>	TxSERCLK to TxSER data delay		230	nS	
t <sub>4</sub>	Rising Edge of TxSERCLK to Rising Edge of TxCH-CLK		13	nS	
t <sub>5</sub>	Rising Edge of TxCHCLK to Valid TxCHN[4:0] Data		6	nS	
t <sub>6</sub>	TxSERCLK to TxSIG delay		230	nS	
t <sub>7</sub>	TxSERCLK to TxFRACT delay		110	nS	



#### FIGURE 1. FRAMER SYSTEM TRANSMIT TIMING DIAGRAM (BASE RATE/NON-MUX)



#### AC ELECTRICAL CHARACTERISTICS RECEIVE FRAMER (BASE RATE/NON-MUX)

SYMBOL	PARAMETER	Min.	TYP.	MAX.	UNITS	CONDITIONS
RxSERCL	K as an Output	, , , 0				
t <sub>8</sub>	Rising Edge of RxSERCLK to Rising Edge of RxCA-SYNC	60		4	nS	
t <sub>9</sub>	Rising Edge of RxSERCLK to Rising Edge of RxCRCSYNC			4	nS	
t <sub>10</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSYNC (RxSYNC as Output)			4	nS	
t <sub>11</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSER			6	nS	
t <sub>12</sub>	Rising Edge of RxSERCLK to Rising Edge of Valid RxCHN[4:0] data			6	nS	
RxSERCL	K as an Input		'			
t <sub>13</sub>	Rising Edge of RxSERCLK to Rising Edge of RxCA-SYNC			8	nS	

T1/E1/J1 BITS ELEMENT - HARDWARE MANUAL

#### AC ELECTRICAL CHARACTERISTICS RECEIVE FRAMER (BASE RATE/NON-MUX)

SYMBOL	PARAMETER	MIN.	TYP.	Max.	Units	CONDITIONS
t <sub>14</sub>	Rising Edge of RxSERCLK to Rising Edge of RxCRCSYNC			8	nS	
t <sub>15</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSYNC (RxSYNC as Output)			10	nS	
t <sub>15</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSYNC (RxSYNC as Input)			230	nS	
t <sub>16</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSER			10	nS	
t <sub>17</sub>	Rising Edge of RxSERCLK to Rising Edge of Valid RxCHN[4:0] data		wis	100	nS	

FIGURE 2. FRAMER SYSTEM RECEIVE TIMING DIAGRAM (RXSERCLK AS AN OUTPUT)

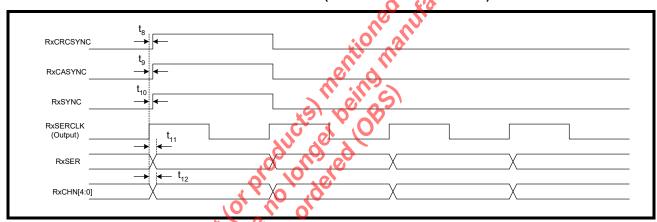
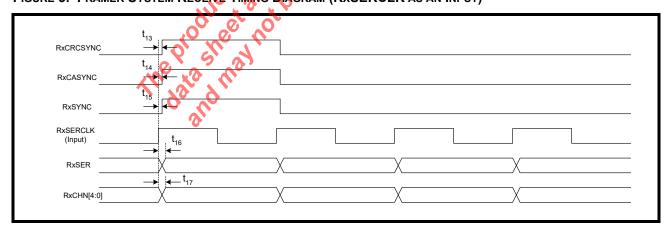


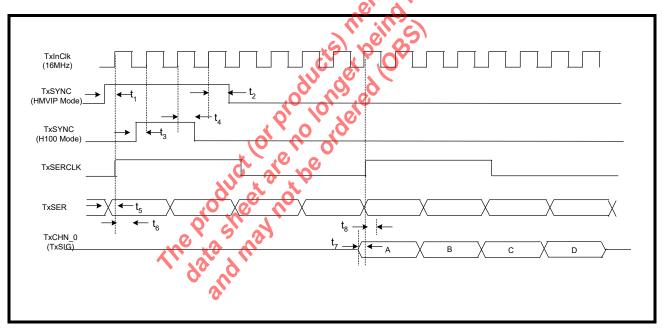
FIGURE 3. FRAMER SYSTEM RECEIVE TIMING DIAGRAM (RXSERCLK AS AN INPUT)



#### AC ELECTRICAL CHARACTERISTICS TRANSMIT FRAMER (HMVIP/H100 MODE)

SYMBOL	PARAMETER	Min.	TYP.	Max.	Units	CONDITIONS
$t_1$	TxSYNC Setup Time - HMVIP Mode	7			nS	
t <sub>2</sub>	TxSYNC Hold Time - HMVIP Mode	4			nS	
t <sub>3</sub>	TxSYNC Setup Time - H100 Mode	7			nS	
$t_4$	TxSYNC Hold Time - H100 Mode	4			nS	
t <sub>5</sub>	TxSER Setup Time - HMVIP and H100 Mode	6			nS	
t <sub>6</sub>	TxSER Hold Time - HMVIP and H100 Mode	3		19 00	nS	
t <sub>7</sub>	TxSIG Setup Time - HMVIP and H100 Mode	6		"UI	nS	
t <sub>8</sub>	TxSIG Hold Time - HMVIP and H100 Mode	3	711	C	nS	

FIGURE 4. FRAMER SYSTEM TRANSMIT TIMING DIAGRAM (HMVIR AND H100 MODE)



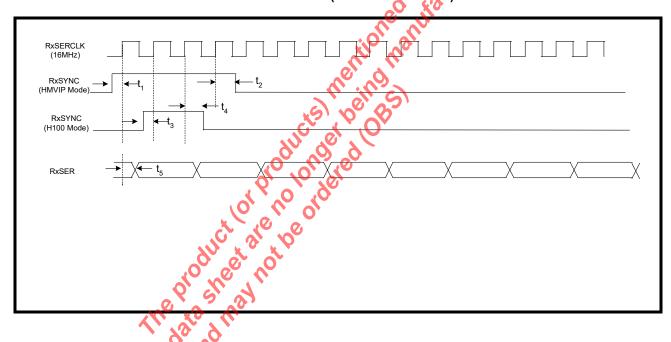
**NOTE:** Setup and Hold time is not valid from TxInClk to TxSERCLK as TxInClk is used as the timing source for the back plane interface and TxSERCLK is used as the timing source on the line side.

#### AC ELECTRICAL CHARACTERISTICS RECEIVE FRAMER (HMVIP/H100 MODE)

SYMBOL	PARAMETER	MIN.	TYP.	Max.	UNITS	CONDITIONS
$t_1$	RxSYNC Setup Time - HMVIP Mode	4			nS	
$t_2$	RxSYNC Hold Time - HMVIP Mode	3			nS	
$t_3$	RxSYNC Setup Time - H100 Mode	5			nS	
t <sub>4</sub>	RxSYNC Hold Time - H100 Mode	3			nS	
t <sub>5</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSER delay		.6	11	nS	

**Note:** Both RxSERCLK and RxSYNC are inputs

FIGURE 5. FRAMER SYSTEM RECEIVE TIMING DIAGRAM (HMVIP/H100 MODE)

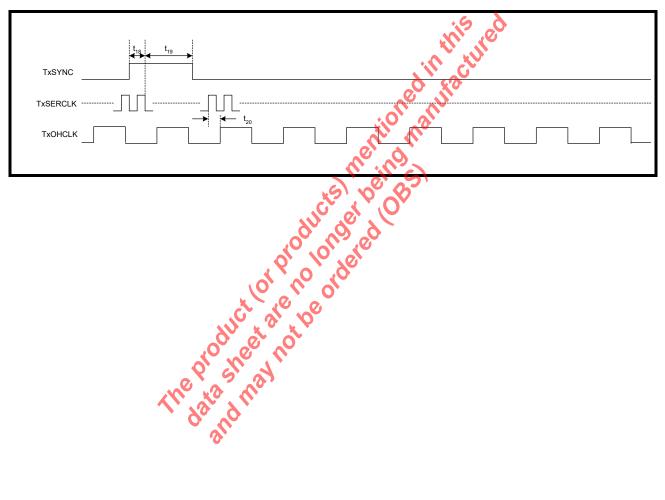




#### AC ELECTRICAL CHARACTERISTICS TRANSMIT OVERHEAD FRAMER

Test Cond	Test Conditions: TA = 25°C, VDD = 3.3V <u>+</u> 5% unless otherwise specified									
SYMBOL	PARAMETER	MIN.	TYP.	Max.	Units	Conditions				
t <sub>18</sub>	TxSYNC Setup Time (Falling Edge TxSERCLK)	6			nS					
t <sub>19</sub>	TxSYNC Hold Time (Falling Edge TxSERCLK)	4			nS					
t <sub>20</sub>	Rising Edge of TxSERCLK to TxOHCLK			12	nS					

#### FIGURE 6. FRAMER SYSTEM TRANSMIT OVERHEAD TIMING DIAGRAM





#### AC ELECTRICAL CHARACTERISTICS RECEIVE OVERHEAD FRAMER

SYMBOL	PARAMETER	MIN.	TYP.	Max.	UNITS	CONDITIONS			
RxSERCLK as an Output									
t <sub>21</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSYNC (RxSYNC as Output)			4	nS				
t <sub>22</sub>	Rising Edge of RxSERCLK to Rising Edge of RxOHCLK			6	nS				
t <sub>23</sub>	Rising Edge of RxSERCLK to Rising Edge of RxOH			8	nS				
RxSERCL	K as an Input		.6	λ	I				
t <sub>24</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSYNC (RxSYNC as Output)	•.	dilli	<b>C</b> 12	nS				
t <sub>24</sub>	Rising Edge of RxSERCLK to Rising Edge of RxSYNC (RxSYNC as Input)	200	Jis.	230	nS				
t <sub>25</sub>	Rising Edge of RxSERCLK to Rising Edge of RxOHCLK	10,40		12	nS				
t <sub>26</sub>	Rising Edge of RxSERCLK to Rising Edge of RxOH	20		15	nS				

FIGURE 7. FRAMER SYSTEM RECEIVE OVERHEAD TIMING DIAGRAM (RXSERCLK AS AN OUTPUT)

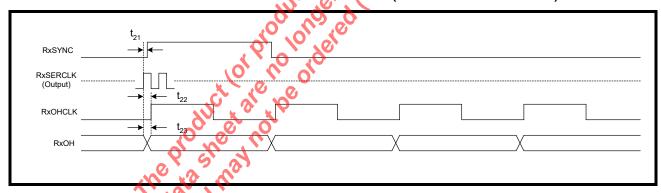


FIGURE 8. FRAMER SYSTEM RECEIVE OVERHEAD TIMING DIAGRAM (RXSERCLK AS AN INPUT)

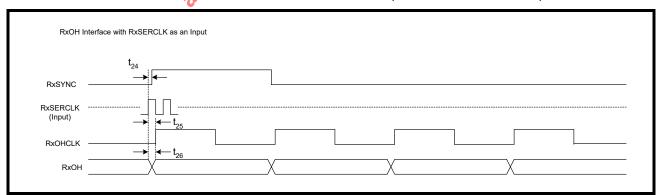


TABLE 2: E1 RECEIVER ELECTRICAL CHARACTERISTICS

PARAMETER	Min.	TYP.	Max.	Unit	TEST CONDITIONS
Receiver loss of signal:					Cable attenuation @1024kHz
Number of consecutive zeros before RLOS is set		32			
Input signal level at RLOS	15	20		dB	ITU-G.775, ETSI 300 233
RLOS De-asserted	12.5			% ones	15 tog
Receiver Sensitivity (Short Haul with cable loss)	11			dB	With nominal pulse amplitude of 3.0V for $120\Omega$ and $2.37V$ for $75\Omega$ application.
Receiver Sensitivity (Long Haul with cable loss) Normal Extended	0	43	38110	dB	With nominal pulse amplitude of 3.0V for $120\Omega$ and $2.37V$ for $75\Omega$ application.
Input Impedance	Ŭ	15		kΩ	
Input Jitter Tolerance: 1 Hz 10kHz-100kHz	37 0.3	oroduct.	Sted C	Ulpp Ulpp	ITU G.823
Recovered Clock Jitter Transfer Corner Frequency Peaking Amplitude	,01	200	0.5	kHz dB	ITU G.736
Jitter Attenuator Corner Frequency (-3dB curve) (JABW=0) (JABW=1)	odvet	10 1.5	-	Hz Hz	ITU G.736
Return Loss: 51kHz - 102kHz 102kHz - 2048kHz 2048kHz - 3072kHz	2 310 8 8 8	-	-	dB dB dB	ITU-G.703

TABLE 3: T1 RECEIVER ELECTRICAL CHARACTERISTICS

PARAMETER	Min.	TYP.	Max.	Unit	TEST CONDITIONS
Receiver loss of signal:					
Number of consecutive zeros before RLOS is set		175			
Input signal level at RLOS	15	20	-	dB	Cable attenuation @772kHz
RLOS Clear	12.5	-	-	% ones	ITU-G.775, ETSI 300 233
Receiver Sensitivity (Short Haul with cable loss)	12	-		dB	With nominal pulse amplitude of 3.0V for $100\Omega$ termination
Receiver Sensitivity (Long Haul with cable loss) Normal Extended	0	45	3670	dB dB	With nominal pulse amplitude of 3.0V for $100\Omega$ termination
Input Impedance		15	e -0	kΩ	
Jitter Tolerance: 1Hz 10kHz - 100kHz	138 0.4	with e	bell be	Ulpp	AT&T Pub 62411
Recovered Clock Jitter Transfer Corner Frequency Peaking Amplitude	or pr	190,00	0.1	KHz dB	TR-TSY-000499
Jitter Attenuator Corner Frequency (-3dB curve)	it do	63		Hz	AT&T Pub 62411
Return Loss: 51kHz - 102kHz 102kHz - 2048kHz 2048kHz - 3072kHz	Way Vo	14 20 16	- - -	dB dB dB	

TABLE 4: E1 TRANSMITTER ELECTRICAL CHARACTERISTICS

PARAMETER	MIN.	TYP.	Max.	Unit	TEST CONDITIONS
AMI Output Pulse Amplitude:					1:2 Transformer
75 $\Omega$ Application	2.13	2.37	2.60	V	
120 $\Omega$ Application	2.70	3.00	3.30	V	
Output Pulse Width	224	244	264	ns	
Output Pulse Width Ratio	0.95	-	1.05	-	ITU-G.703
Output Pulse Amplitude Ratio	0.95	-	1.05	-	ITU-G.703
Jitter Added by the Transmitter Output	-	0.025	0.05	Ulpp	Broad Band with jitter free TCLK applied to the input.
Output Return Loss:				10	
51kHz -102kHz	15	-	-	dB	E7SI 300 166
102kHz-2048kHz	9	-	-	dB	
2048kHz-3072kHz	8	-		dB	

TABLE 5: E1 TRANSMIT RETURN LOSS REQUIREMENT

RETURN LOSS ETS 300166
6dB
8dB
8dB
Anot be

TABLE 6: T1 TRANSMITTER ELECTRICAL CHARACTERISTICS

PARAMETER	Min.	TYP.	Max.	Unit	TEST CONDITIONS
AMI Output Pulse Amplitude:	2.4	3.0	3.60	V	1:2 Transformer measured at DSX_1.
Output Pulse Width	338	350	362	ns	ANSI T1.102
Output Pulse Width Imbalance	-	-	20	-	ANSI T1.102
Output Pulse Amplitude Imbalance	-	-	<u>+</u> 200	mV	ANSI T1.102
Jitter Added by the Transmitter Output	-	0.025	0.05	Ulpp	Broad Band with jitter free TCLK applied to the input.
Output Return Loss: 51kHz -102kHz 102kHz-2048kHz 2048kHz-3072kHz	- - -	17 12 10	- - -	dB dB dB	tured
		6	Sell'o	ارق	
51kHz -102kHz 102kHz-2048kHz 2048kHz-3072kHz  The dradite	Corpio	ducts), olonder peorde	bell be	5	

FIGURE 9. ITU G.703 PULSE TEMPLATE

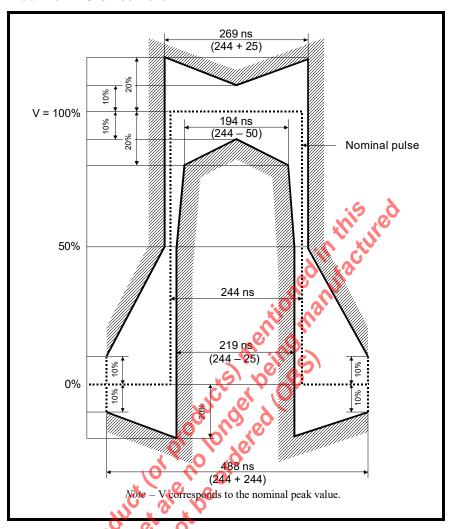


TABLE 7: TRANSMIT PULSE MASK SPECIFICATION

Test Load Impedance	75Ω Resistive (Coax)	120 $\Omega$ Resistive (twisted Pair)
Nominal Peak Voltage of a Mark	2.37V	3.0V
Peak voltage of a Space (no Mark)	0 <u>+</u> 0.237V	0 <u>+</u> 0.3V
Nominal Pulse width	244ns	244ns
Ratio of Positive and Negative Pulses Imbalance	0.95 to 1.05	0.95 to 1.05

FIGURE 10. ITU G.703 SECTION 13 SYNCHRONOUS INTERFACE PULSE TEMPLATE

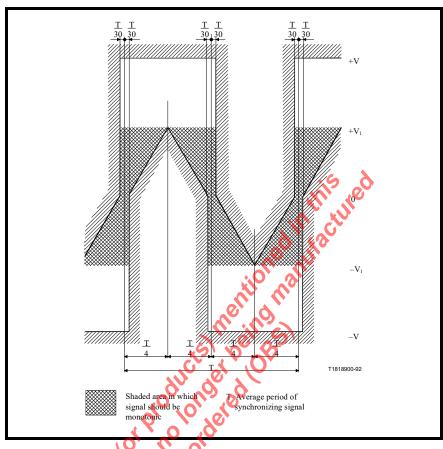


TABLE 8: E1 SYNCHRONOUS INTERFACE TRANSMIT PULSE MASK SPECIFICATION

Test Load Impedance	75Ω Resistive (Coax)	120 $\Omega$ Resistive (twisted Pair)
Maximum Peak Voltage of a Mark	1.5V	1.9V
Minimum Peak Voltage of a Mark	0.75V	1.0V
Nominal Pulse width	244ns	244ns

FIGURE 11. DSX-1 PULSE TEMPLATE (NORMALIZED AMPLITUDE)

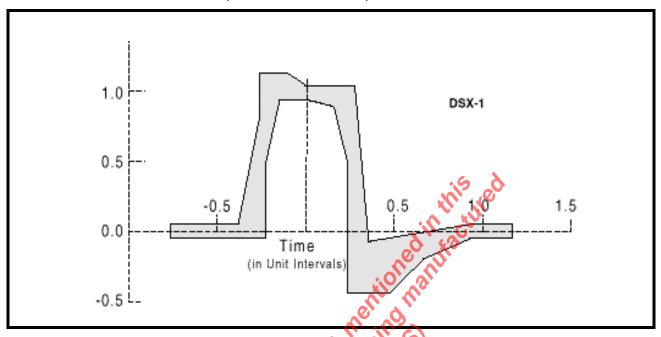


TABLE 9: DSX1 INTERFACE ISOLATED PULSE MASK AND CORNER POINTS

	MINIMUM CURVE	0 0	MAXIMUM CURVE
TIME (UI)	NORMALIZED AMPLITUDE	TIME (UI)	NORMALIZED AMPLITUDE
-0.77	05V	-0.77	.05V
-0.23	05V	-0.39	.05V
-0.23	0.5V	-0.27	.8V
-0.15	0.95	-0.27	1.15V
0.0	0.95V	-0.12	1.15V
0.15	0.9V	0.0	1.05V
0.23	<b>0.5</b> V	0.27	1.05V
0.23	-0.45V	0.35	-0.07V
0.46	-0.45V	0.93	0.05V
0.66	-0.2V	1.16	0.05V
0.93	-0.05V		
1.16	-0.05V		

**TABLE 10: AC ELECTRICAL CHARACTERISTICS** 

$VDD_{IO}$ = 3.3V $\pm$ 5% , $VDD_{CORE}$ = 1.8V $\pm$ 5%, Ta=25°C, unless otherwise specified					
PARAMETER	SYMBOL	Min.	TYP.	Max.	Units
MCLKIN Clock Duty Cycle		40	-	60	%
MCLKIN Clock Tolerance		-	±50	-	ppm

The product are no ordered (OES)

#### MICROPROCESSOR INTERFACE I/O TIMING

#### **INTEL INTERFACE TIMING - ASYNCHRONOUS**

The signals used for the Intel microprocessor interface are: Address Latch Enable (ALE), Read Enable (RD), Write Enable (WR), Chip Select (CS), Address and Data bits. The microprocessor interface uses minimum external glue logic and is compatible with the timings of the 8051 or 80188 family of microprocessors. The ALE signal can be tied 'HIGH' if this signal is not available, and the corresponding timing interface is shown in Figure 13 and Table 12.

FIGURE 12. INTEL MP INTERFACE TIMING DURING PROGRAMMED I/O READ AND WRITE OPERATIONS WHEN ALE IS NOT TIED 'HIGH'

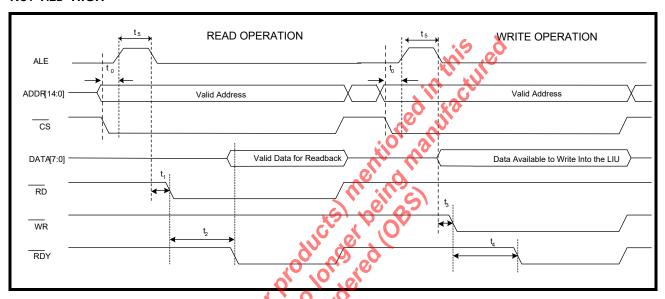


TABLE 11: INTEL MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS

SYMBOL	PARAMETER	Min	Max	Units
t <sub>0</sub>	Valid Address to CS Falling Edge and ALE Rising Edge	0	-	ns
t <sub>1</sub>	ALE Falling Edge to RD Assert	5	-	ns
t <sub>2</sub>	RD Assert to RDY Assert	-	320	ns
NA	RD Pulse Width (t <sub>2</sub> )	320	-	ns
t <sub>3</sub>	ALE Falling Edge to WR Assert	5	-	ns
t <sub>4</sub>	WR Assert to RDY Assert	-	320	ns
NA	WR Pulse Width (t <sub>4</sub> )	320	-	ns
t <sub>5</sub>	ALE Pulse Width(t <sub>5</sub> )	10		ns

REV. 1.0.5 T1/E1/J1 BI

FIGURE 13. INTEL MP INTERFACE TIMING DURING PROGRAMMED I/O READ AND WRITE OPERATIONS WHEN ALE IS TIED 'HIGH'

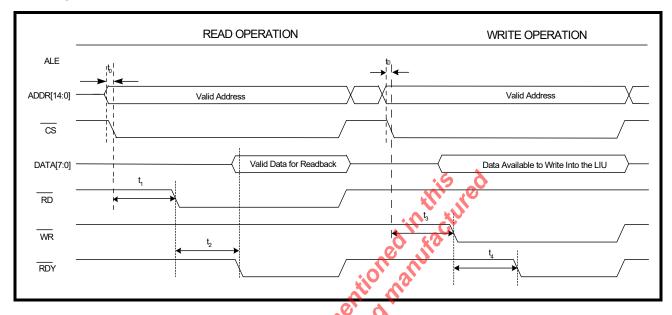


TABLE 12: INTEL MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS

SYMBOL	PARAMETER AND A CONTROL OF A CO	Min	Max	Units
t <sub>0</sub>	Valid Address to CS Falling Edge	0	-	ns
t <sub>1</sub>	CS Falling Edge to RD Assert	0	-	ns
t <sub>2</sub>	RD Assert to RDY Assert	-	320	ns
NA	RD Pulse Width (t <sub>2</sub> )	320	-	ns
t <sub>3</sub>	CS Falling Edge to WR Assert	0	-	ns
t <sub>4</sub>	WR Assert to RDY Assert	-	320	ns
NA	WR Pulse Width (t₄)	320	-	ns



#### MOTOROLA ASYCHRONOUS INTERFACE TIMING

The signals used in the Motorola microprocessor interface mode are: Address Strobe (AS), Data Strobe ( $\overline{DS}$ ), Read/Write Enable (R/W), Chip Select ( $\overline{CS}$ ), Address and Data bits. The interface is compatible with the timing of a Motorola 68000 microprocessor family. The interface timing is shown in Figure 14. The I/O specifications are shown in Table 13.

FIGURE 14. MOTOROLA ASYCHRONOUS MODE INTERFACE SIGNALS DURING PROGRAMMED I/O READ AND WRITE OPERATIONS

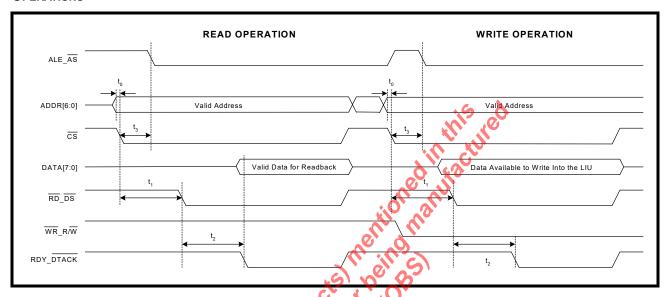


TABLE 13: MOTOROLA ASYCHRONOUS MODE MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS

SYMBOL	PARAMETER	Min	Max	Units
t <sub>0</sub>	Valid Address to CS Falling Edge	0	-	ns
t <sub>1</sub>	CS Falling Edge to DS (Pin RD_DS) Assert	0	-	ns
t <sub>2</sub>	DS Assert to DTACK Assert	-	320	ns
NA	DS Pulse Width (t <sub>2</sub> )	320	-	ns
t <sub>3</sub>	CS Falling Edge to AS (Pin ALE AS) Falling Edge	0	-	ns



#### POWER PC 403 SYCHRONOUS INTERFACE TIMING

The signals used in the Power PC 403 Synchronus microprocessor interface mode are: Address Strobe (AS), Microprocessor Clock (uPCLK), Data Strobe (DS), Read/Write Enable (R/W), Chip Select (CS), Address and Data bits. The interface timing is shown in Figure 15. The I/O specifications are shown in Table 14.

FIGURE 15. POWER PC 403 INTERFACE SIGNALS DURING PROGRAMMED I/O READ AND WRITE OPERATIONS

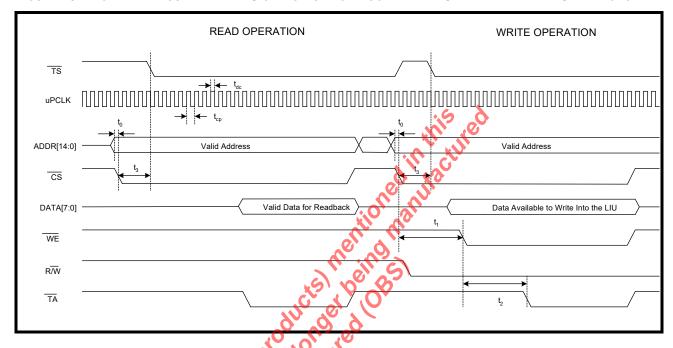


TABLE 14: POWER PC 403 MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS

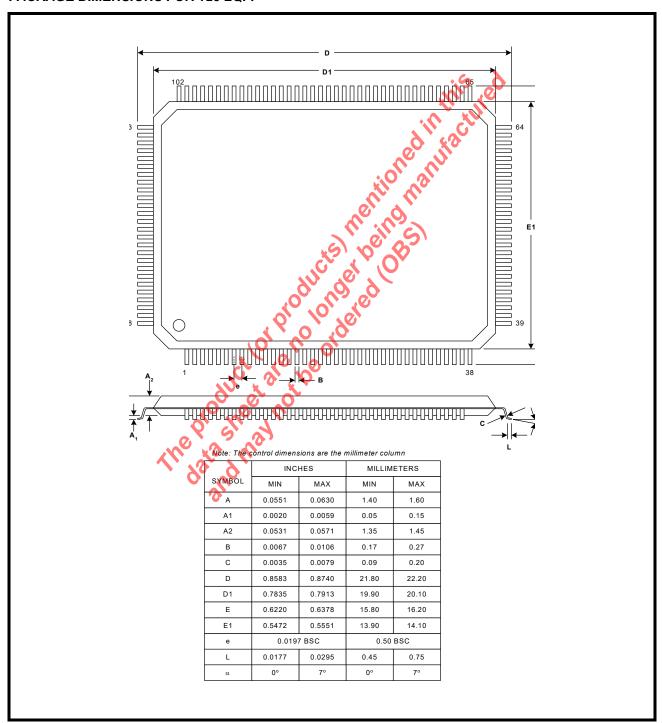
SYMBOL	PARAMETER	Min	MAX	Units
t <sub>0</sub>	Valid Address to CS Falling Edge	0	-	ns
t <sub>1</sub>	CS Falling Edge to WE Assert	0	-	ns
t <sub>2</sub>	WE Assert to TA Assert	-	320	ns
NA	WE Pulse Width (t <sub>2</sub> )	320	-	ns
t <sub>3</sub>	CS Falling Edge to TS Falling Edge	0	-	
t <sub>dc</sub>	μPCLK Duty Cycle	40	60	%
t <sub>cp</sub>	μPCLK Clock Period	20	-	ns



#### ORDERING INFORMATION

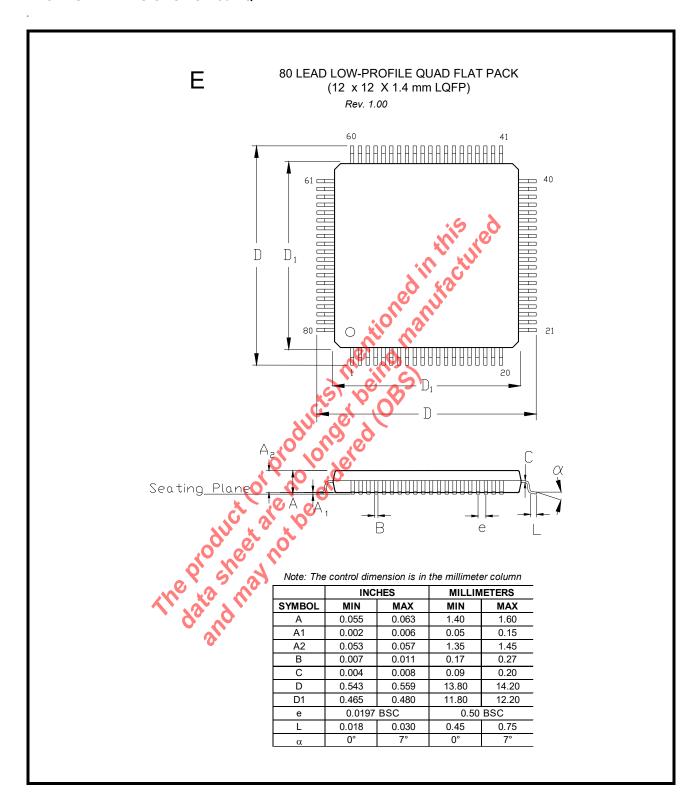
PRODUCT NUMBER	PACKAGE	OPERATING TEMPERATURE RANGE
XRT86VL30IV-F	128 Pln LQFP (14x20x1.4mm)	-40°C to +85°C
XRT86VL30IV80-F	80 Pin LQFP (12x12x1.4mm)	-40°C to +85°C

#### PACKAGE DIMENSIONS FOR 128 LQFP





#### PACKAGE DIMENSIONS FOR 80 LQFP



#### **REVISION HISTORY**

REVISION #	DATE	DESCRIPTION
1.0.0	May 30,2008	Initial release of the XRT86VL30 datasheet.
1.0.1	August 08, 2008	Remove SPI functionality descriptions from data sheet.
1.0.2	August 15, 2008	Update Pin Description tables with pin number information for 80pin package.
1.03	September 9, 2008	Update power consumption numbers and thermal characteristics in electrical table.
1.0.4	December 18, 2009	80-pin Package  1. Removed reference to TRST on page 29 (removed note to ground this pin)  2. Added pin 71 to DGND list on page 37
1.0.5	April 6, 2021	Updated the part numbers in the Ordering Information tables.

1.0.5 April 6, 2021 Updated the part numbers in the Ordering information tables.

NOTICE

EXAR Corporation reserves the right to make changes to the products contained in this publication in order to improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein converse the literage updated are represented to the control of improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein, conveys no license under any patent or other right, and makes no representation that the circuits are free of patent infringement. Charts and schedules contained here in are only for illustration purposes and may vary depending upon a user's specific application. While the information in this publication has been carefully checked; no responsibility, however, is assumed for inaccuracies.

EXAR Corporation does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless EXAR Corporation receives, in writing, assurances to its satisfaction that: (a) the risk of injury or damage has been minimized; (b) the user assumes all such risks; (c) potential liability of EXAR Corporation is adequately protected under the circumstances.

Copyright 2021 EXAR Corporation

Datasheet April 6, 2021.

Reproduction, in part or whole, without the prior written consent of EXAR Corporation is prohibited.